# 0.11 Campbell SR50 Sonic Snow Depth Gauge Quick Reference

## Description

The SR50 sensor is an intelligent sensor which uses a 50kHz electrostatic transducer to measure distance. An internal microprocessor can be programmed to filter the data in order to obtain higher quality output.

The output of the sensor is an SDI-12 serial message, with measurement data in meters. The reading must be corrected for air temperature by the following equation:

Distance = Reading \* sqrt(T(degK)/273.15)

On the PAM GAME station this is done in EVE using the temperature from TRH probe 1. In the CR10X program supplied to GAME the instrument uses SDI-12 instruction 8. If the ground or snow base is not found, the instrument will return a 0.

## **Specifications**

Power Input: 9-16VDC

Power Consumption: 2mA (quiescent)

250 mA (measurement peak)

Measurement Time: .6 sec to 3 seconds max

Viewing Angle: 22 degrees

Output: SDI-12 or Pulse Train

SDI-12 data is in meters or feet

Range: 0.5 to 10 meters

Accuracy: +/- 1 cm or 0.4% of reading

#### SDI-12 Commands (Partial List)

CR10- P105	Function	Output
Parameter 2		
0	First Target	D1
8	First Target no retries	D1

#### Installation

The sensor should be mounted on a sturdy platform. Vibrations can reduce the accuracy of the reading. The sensor should be mounted perpendicular to the surface, and as close to it as possible, but at least 0.5 meters away. Once the sensor is attached and running, a manual measurement should be done to ensure the output accuracy.

# Wiring

Color	Function	Connector Pin	Logger
====	=====	========	=====
Black	ground	1	ground
Red	+12V	2	+12V
Green	SDI-12 bus	4	control port
White	ground	3	ground
Clear	shield	5	ground

The sensor should be connected to the CR10X box to the SNOW depth port.

# Maintenance

Dessicant in the sensor should be replaced yearly, or more often if the sensor is used in a humid environment. See the SR50 manual for information on disassembling the sensor to replace the dessicant.