



Convair580 IKP2 data set and background humidity

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IKP-2 installation on the NRC Convair580





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Water vapor inlet

- Double inlet
- Reverse flow
- Shroud protecting from shedding water

During parking rain water got inside the humidity sampling tubing. This resulted in degradation of the background humidity measurements.

After the problem was identified and reverse purging was applied prior take off to dry out the sampling lines. This resolved accurate measurements of background humidity





Performance matrix of the IKP and background humidity measurements

Flight#	7	8	9	10	11	12	13	14	15	16	17	18	19	20
Date	10-May-15	12-May-1	14-May-15	15-May-15	16-May-15	16-May-15	20-May-15	23-May-15	23-May-15	25-May-15	26-May-15	26-May-15	27-May-15	27-May-15
ІКР	Y-	Y	N	N	Y	Y	Y	Y	Y	Y	Y	Y	Y	Y
Licor 840A/ 6262	N	N	N	N	N	N	N	N	N	Y	Y	Y	Y	Y
Chilled Mirror	M-	M-	M-	M-	M-	M-	M-	M+	M+	Y	Y	Y	Y	Y

- With the exception two days, the IKP performance during the Cayenne field deployment was satisfactory
- The background humidity measurements failed during the first half of the field campaign, and it was recovered during the second half.
- $TWC_{IKP} = F(RH_{IKP} RH_{bkgr}, T, P)$
- Existing errors in T and P measurements have minor effect on the TWC_{IKP} accuracy. However, TWC_{IKP} calculations are sensitive to the accuracy of RH_{bkgr}.
- What technique could be used to estimate the background humidity in ice clouds to recover the TWC IKP measurements?





Outline

- Basic IKP data processing (flights with good background humidity) (a) Evaluation of the quality of background humidity
 - (b) Data synchronizations
 - (c) Adjustment of background humidity
 - (d) Air temperature adjustment
- 2. Techniques to estimate background humidity (no background humidity) (a) Saturation humidity at air temperature
 - (b) Air temperature adjustment
 - (c) Quasi-steady humidity
- 3. Accuracy of different techniques, error analysis
- 4. Conclusions







Effect of synchronisation on IKP TWC calculations in clear sky







Effect of background humidity corrections on IKP TWC calculations

IKP and background humidity measurements in clear sky







Adjustment of the background humidity to align with the IKP humidity in clear sky







Effect of background humidity corrections on IKP TWC calculations







IKP response in clear sky









IWC_{IKP} calculations in absence of background humidity measurements







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Supersaturation of Water Vapor in Clouds

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(Manuscript received 18 October 2002, in final form 2

ABSTRACT

A theoretical framework is developed to estimate the supersaturation in lik An equation describing supersaturation in mixed-phase clouds in general for for this equation is obtained for the case of quasi-steady approximation, that is It is shown that the supersaturation asymptotically approaches the quasi-stea creates a basis for the estimation of the supersaturation in clouds from the q lations. The quasi-steady supersaturation is a function of the vertical veloci and ice particles, which can be obtained from in situ measurements. It is sl the evaporating droplets maintain the water vapor pressure close to saturat analytical estimation of the time of glaciation of mixed-phase clouds. The 1 proximation in clouds with different phase composition are considered here, as well as the effect of the characteristic time and spatial scales of turbulent

Theoretical framework describing phase transformation of a three-phase colloidal system.

activation of droplets and then monotonically decreases. Squires (1952) derived a relationship between supply and depletion of water vapor in a vertically moving cloud parcel. The solution of the Squires equation suggested that, to a first approximation, the supersaturation is linearly related to a vertical velocity and inversely proportional to the concentration and the average size of the cloud droplets. This relationship was later used

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Experimental justification of the KM2003 theoretical analysis

1. Introduction

Water vapor insi

life cycle and precipitation formation. The understanding of the relationships between the vapor pressure and microphysical characteristics of clouds is one of the key

circulation models (GCMs) is usually specified as a function of temperature (e.g., Fowler et al. 1996; Jakob

The foregoing analysis is based on the following two studies

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Relative Humidity in Liquid, Mixed-Phase, and Ice Clouds

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ABSTRACT

The results of in situ observations of the relative humidity in liquid, mixed, and ice clouds typically stratiform in nature and associated with mesoscale frontal systems at temperatures $-45^{\circ}C < T_a < -5^{\circ}C$ are presented. The data were collected with the help of instrumentation deployed on the National Research Council (NRC) Convair-580. The length of sampled in-cloud space is approximately 23×10^3 km. The liquid sensor was calibrated in liquid clouds with the assumption that the air in liquid clouds is saturated with respect to water. It was found that the relative humidity in mixed-phase clouds is close to saturation over water in the temperature range from -5° to -35° C for an averaging scale of 100 m. In ice clouds the relative humidity over ice is not necessarily equal to 100%, and it may be either lower or higher than saturation over ice, but it is always lower than saturation over water. On average the relative humidity in ice clouds

increases saturatio large fra undersat







Equilibrium vapor supersaturation, which the humid air in ice cloud tends to approach.

 S_{qsi} depends on vertical velocity \underline{u}_{z} and integral particle radius $N_{i}r_{i}$

Time of phase relaxation determines the characteristic time of relative humidity approaching to its equilibrium value S_{qsi}

Korolev and Mazin, 2003



Statistics of humidity clouds



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In ice clouds due to large time of phase relaxation the air can be both undersaturated or supersaturated with respect to ice,

i.e. possible both $T_{air} < T_{frost}$ or $T_{air} > T_{frost}$

Average RH in mixed phase clouds



In liquid and mixed phase cloud the air in most cases is close to saturation with respect to water, i.e $T_{air} \approx T_{dew}$

Korolev and Isaac (JAS, 2006)





Two approaches to estimate background humidity

- 1. Quasi-steady humidity $RH_i = aU_z/N_ir_i + 1$, where U_z is the vertical velocity of the cloud volume and N_ir_i is the integral particle radius.
- 2. Based on the assumption that humidity in ice clouds is saturated with respect to ice RH_i =1, which means that $T_{air} = T_{frost}$. This assumption presumes that the time of phase relaxation τ_{ph} is short enough (or $N_i r_i$ is large).







Dependence of $N_i r_i$ vs *IWC* for all Convair580 flights at -15C<T<-5C



anticipated large IWC errors





Time of phase relaxation calculated for different IWC thresholds







Average time of phase relaxation calculated for all Convair580 flights

IWC > IWC_{thresh}







Estimation of the error in IWC_{IKP} calculations for the background humidity in assumption $T_{air}=T_{frost}$

 $\Delta IWC = IWC_{IKP}$ (backgrLicor) - IWC_{IKP}(RH_i=S_{qs}+1)





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Effect of the temperature errors dT on the accuracy of IWC calculations in assumption that $T_{air} = T_{frost}$



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Deviation of T_{air} from T_{frost} in ice clouds for different IWC threshold for the Convair580 flights with good background humidity



Distributions of Δ RHi in ice clouds in assumption $T_{air} = T_{frost}$ for different IWC threshold for the Convair580 flights with good background humidity



-15C<T<-5C



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Error in IWC_{IKP} calculations in assumption $T_{air} = T_{frost}$ for different IWC threshold for the Convair580 flights with good background humidity

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Estimation of the error in IWC_{IKP} calculations for the background humidity in assumption $T_{air}=T_{frost}$

 $\Delta IWC = IWC_{IKP}$ (backgrLicor) - IWC_{IKP}(Tair=Tfrost)



Comparisons of three ways of RH estimates in calculations of IWC_{IKP} : (a) background RH; (b) RH($T_{air} = T_{frost}$); (c) RH_i = S_{qs} +1















Overall assessment of accuracy of two methods for IWC>0.1g/m³



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Conclusions

- 1. Accuracy of IWC_{IKP} with the Licor background humidity is estimated as 0.05g/m³ based on the assessment of noise in clear sky at -15C <T <-5C. This error estimate represents random error, and it does not include regular biases which may occur during measurements in clouds.
- 2. In absence of instrumental measurements of background humidity, *RH* can be estimated: (a) from quasi-steady humidity $RH_i = aU_z/N_ir_i + 1$; (b) from assumption $T_{air} = T_{frost}$.
- 3. The first method requires additional measurements of the vertical velocity U_z and calculation of the integral particle size $N_i r_i$ from PSDs measurements. These additional measurements may degrade accuracy of IWC_{IKP} due to errors in $N_i r_i$ and U_z
- 4. The second method is more robust and it provides a slightly better accuracy, than the first method. Average error of the IWC_{IKP} is decreasing with increase of IWC. IWC<0.2g/m3 should not be used as unreliable.
- 5. For future IKP measurements it is recommended using isokinetic (open path) background humidity measurements.







High Ice Water Content (HIWC) Program

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Background humidity measurements







IKP data quality control

Stability of the IKP isokinetic factor







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IKP data quality control

Performance of the IKP and background humidity measurements





