

Deepwave GV flux measurements: methods and uncertainties

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NCAR/EOL

Deepwave PIs: Fritts, Doyle, Eckermann,
Taylor, et al.

Boulder Workshop, October 23, 24 2014

DEEPWAVE GV statistics

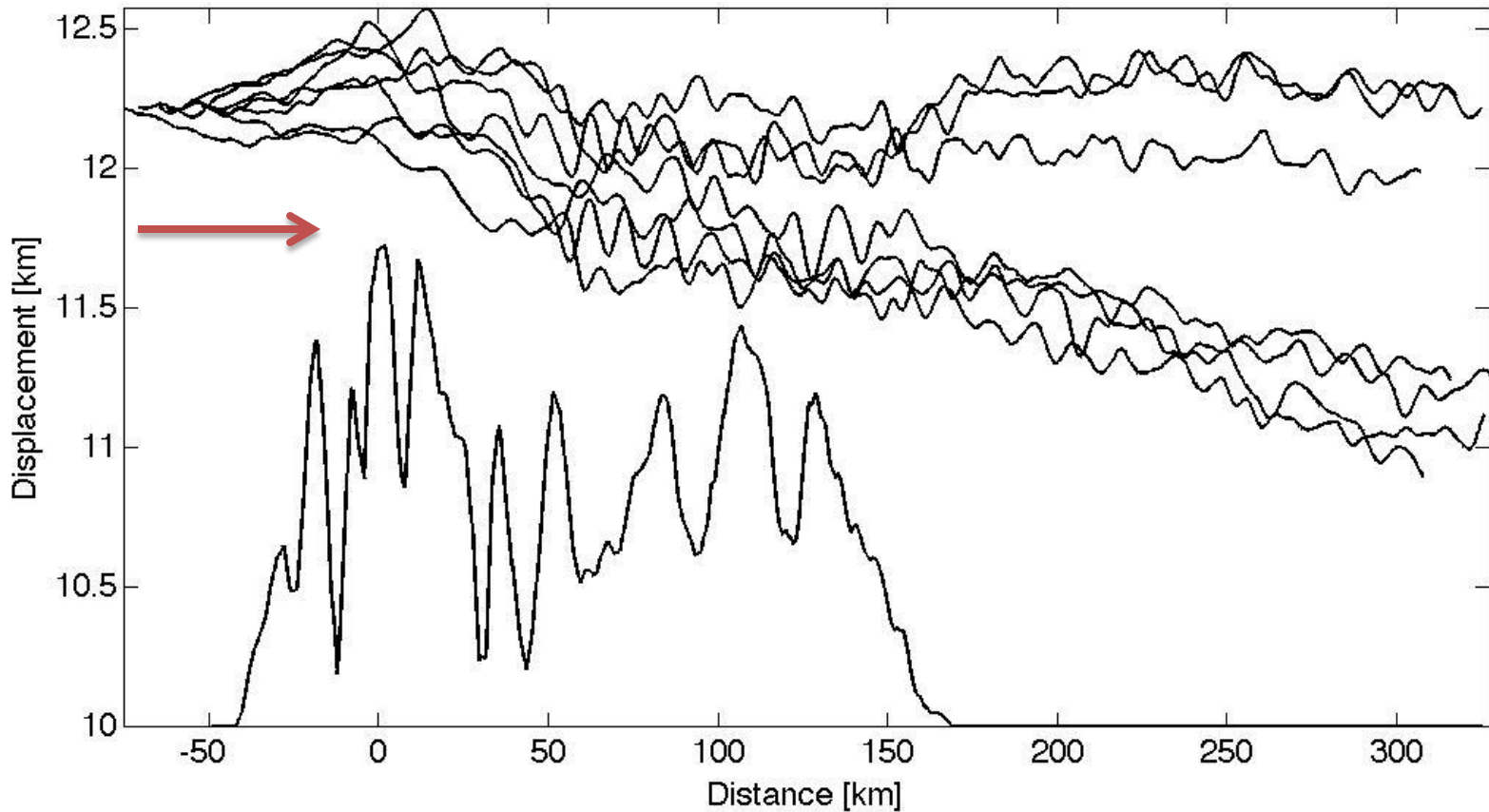
- Location: New Zealand and surrounding ocean
- Observing period: SH Winter; June/July 2014
- Aircraft: NSF/NCAR GV (26 flights, 180 hours)
- Typical leg: length=350km, altitude= 12.1km
- GV Survey legs
 - **Over New Zealand (97 legs; 49.1 hours)**
 - Over Ocean (157 legs; 84.3 hours)

Types of analyses

1. Vertical displacement curves
2. Flux computations
3. Transience
4. Eliassen-Palm check (Bernoulli check)
5. Direction of horizontal EF
6. Pressure analysis for Energy Flux
7. Wavelet scale analysis
8. Reverse fluxes
9. Effect of leg length

RF04: 7 legs over Mt Aspiring

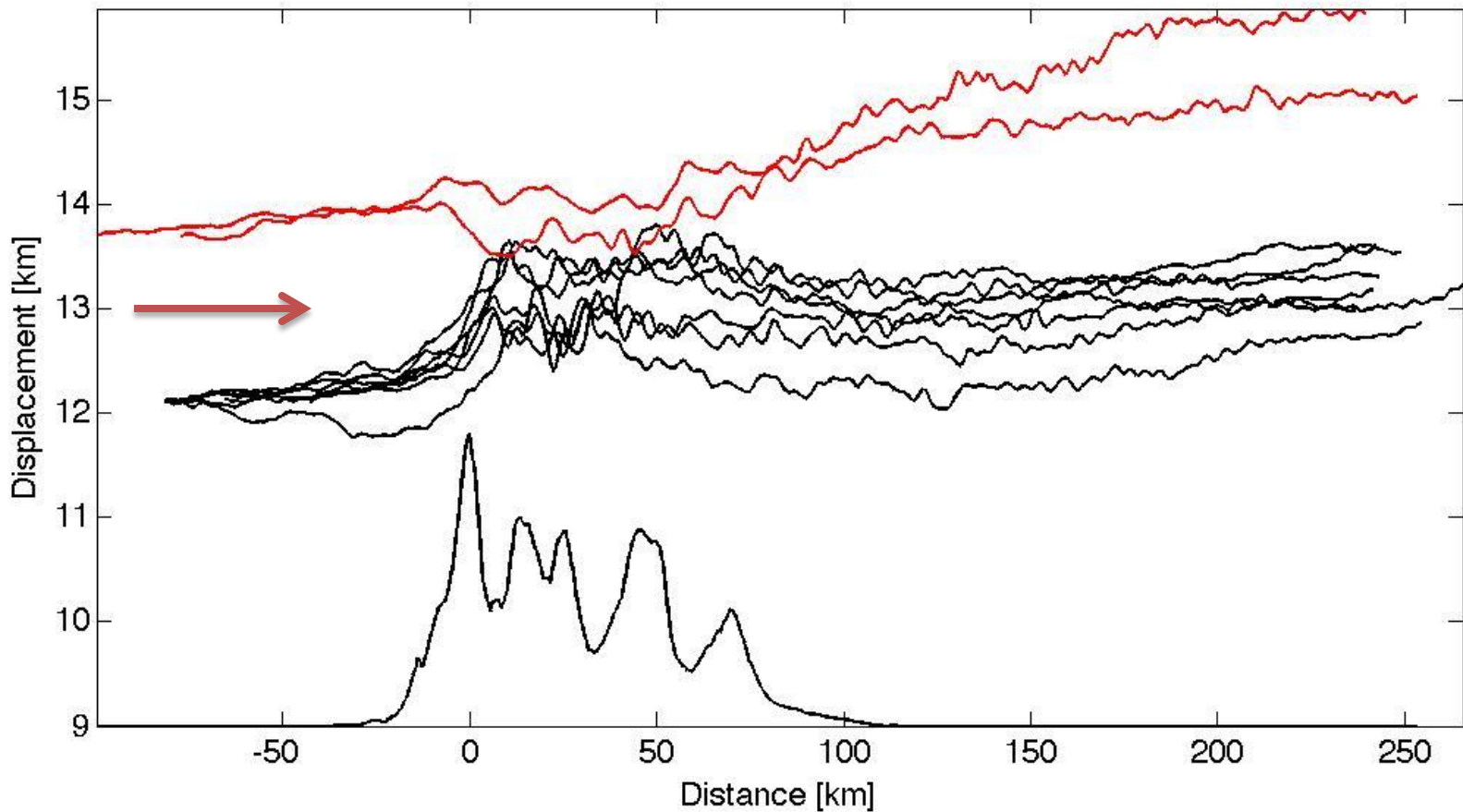
Vertical displacement (estimated)



Mountain to scale but offset vertically

RF05: 9 Legs over Mt Cook

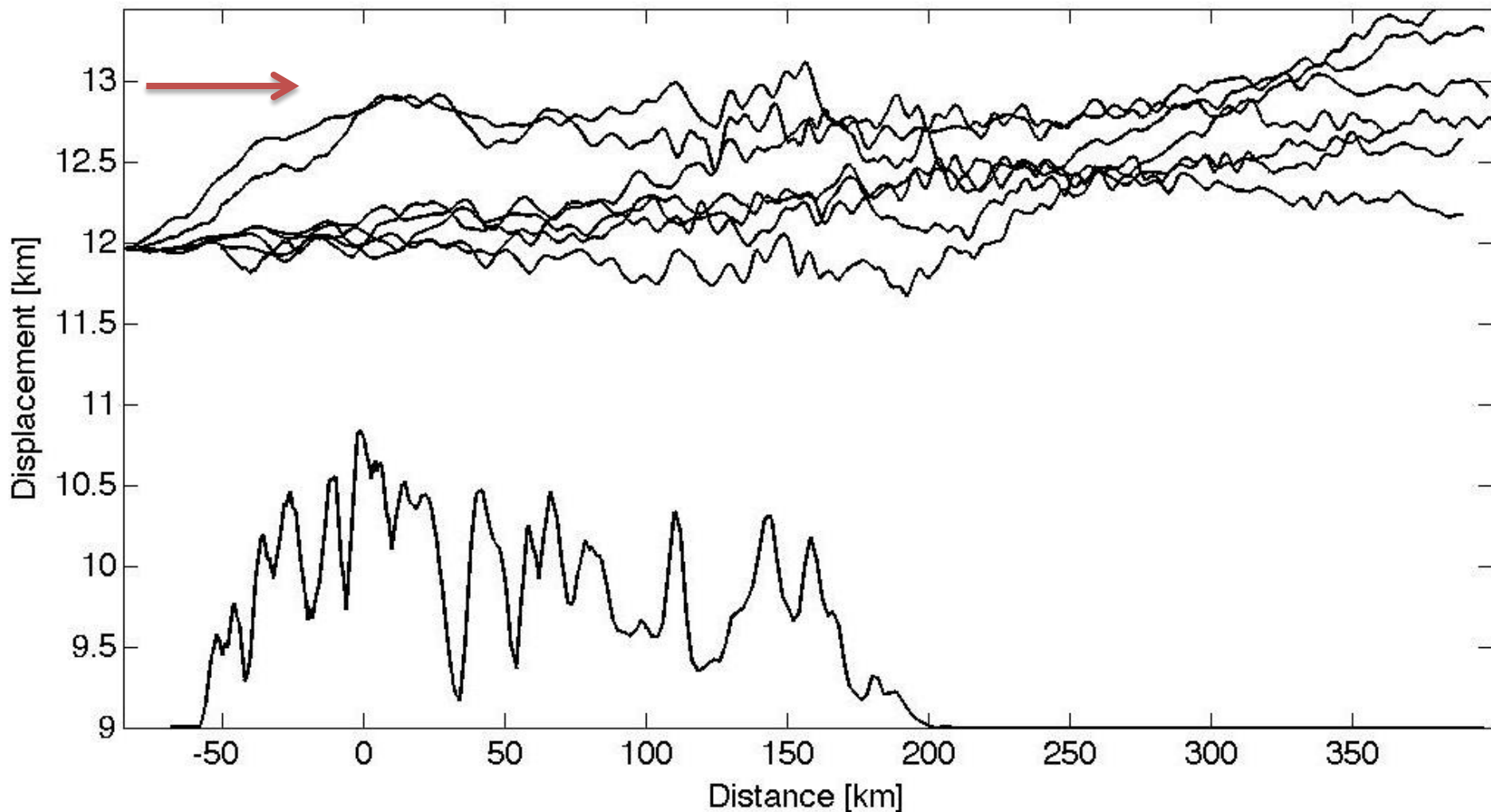
Vertical displacement



Mountain to scale but offset vertically

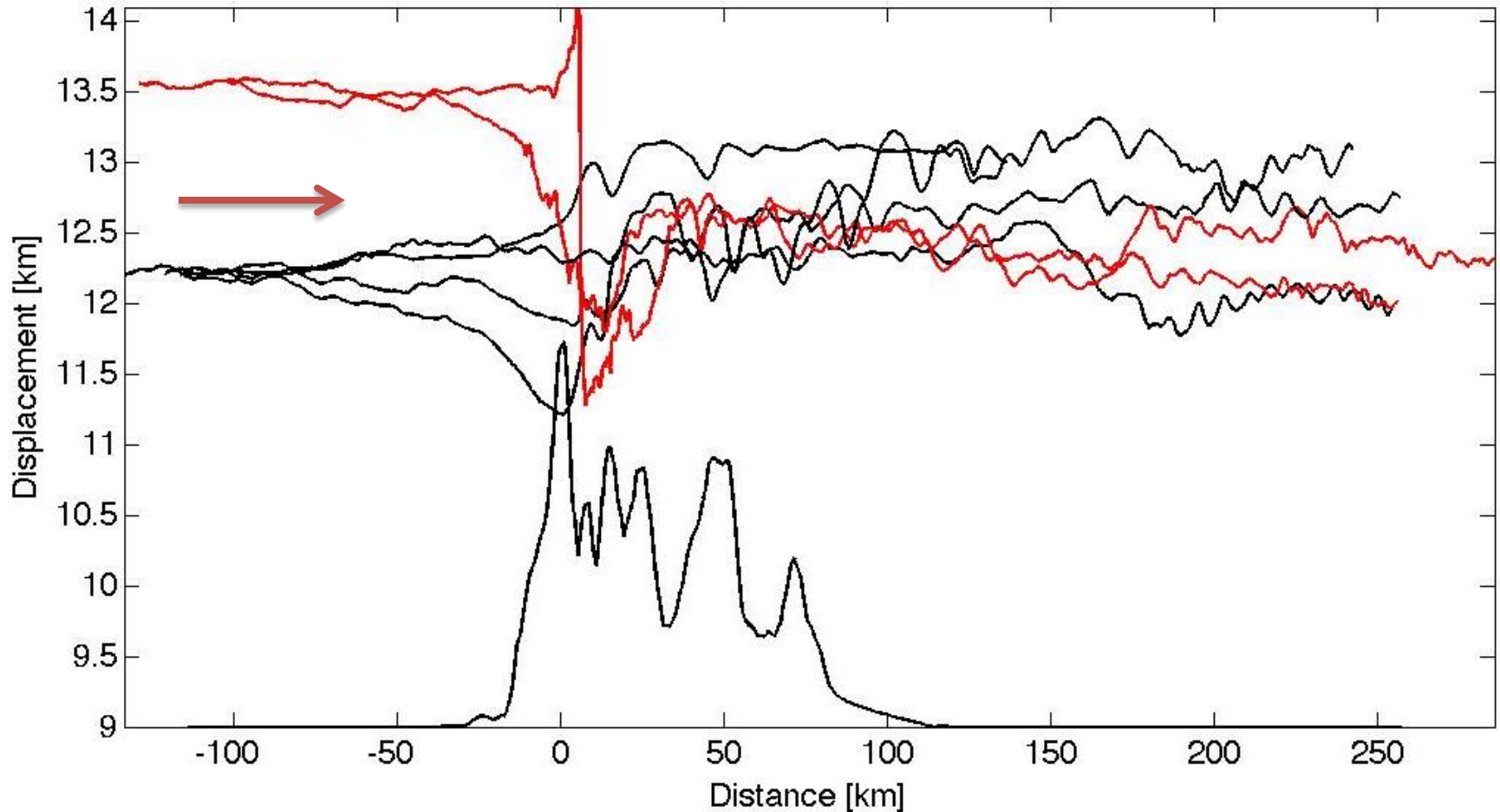
RF08: 7 Legs over Mt Aspiring

Vertical displacement



RF09: 6 legs over Mt Cook

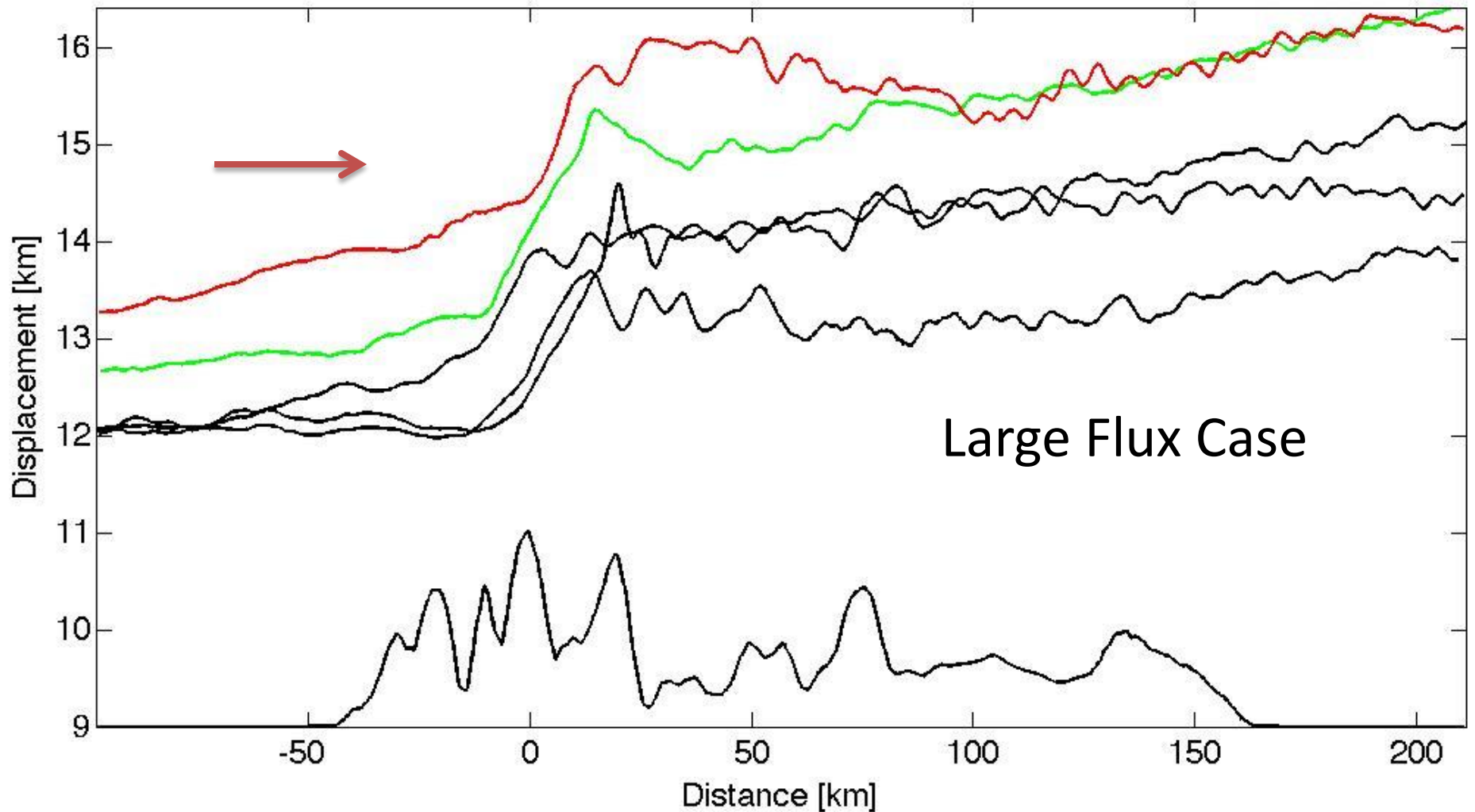
Vertical displacement



Mountain to scale but offset vertically

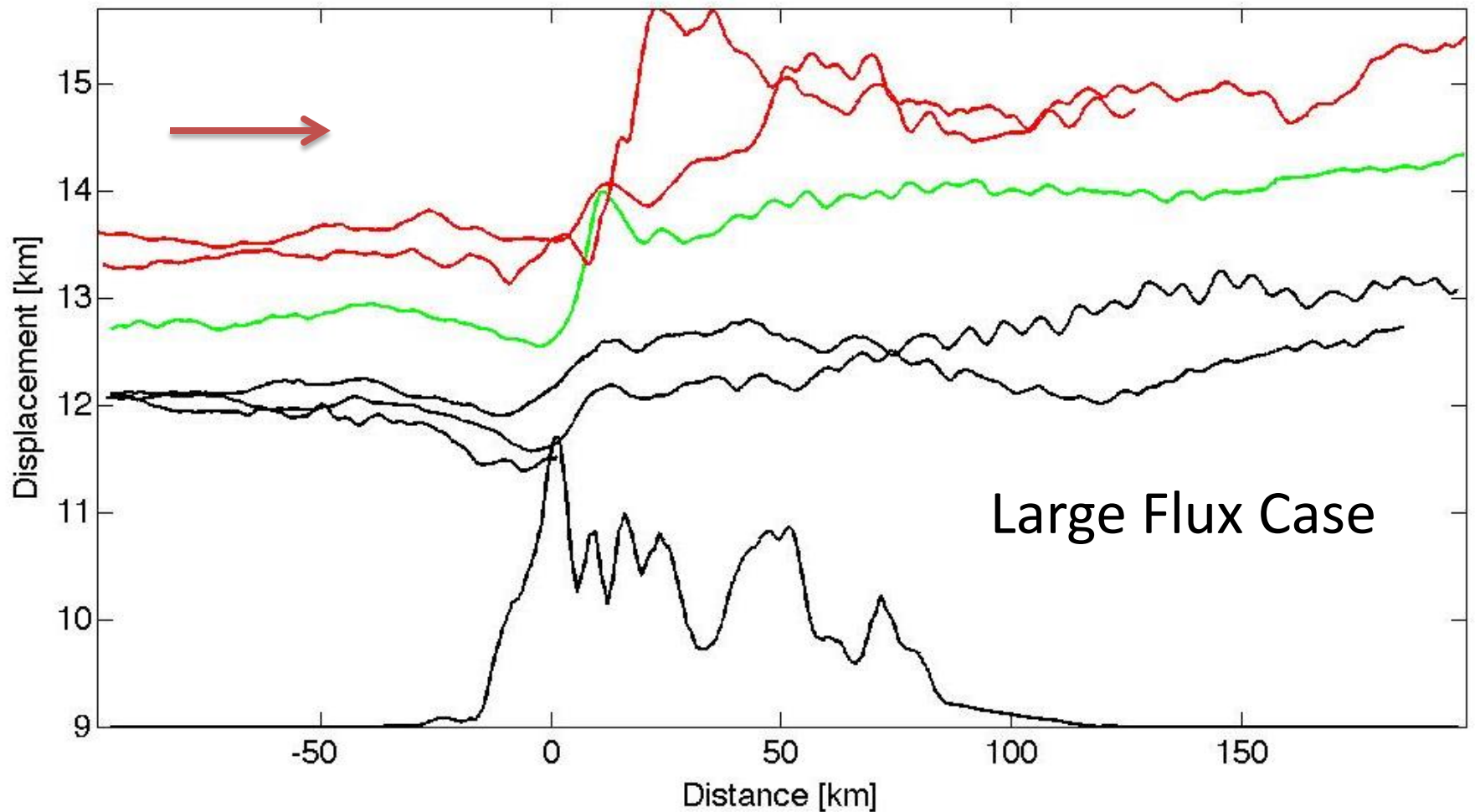
RF012: 5 legs over Mt Aspiring

Vertical displacement



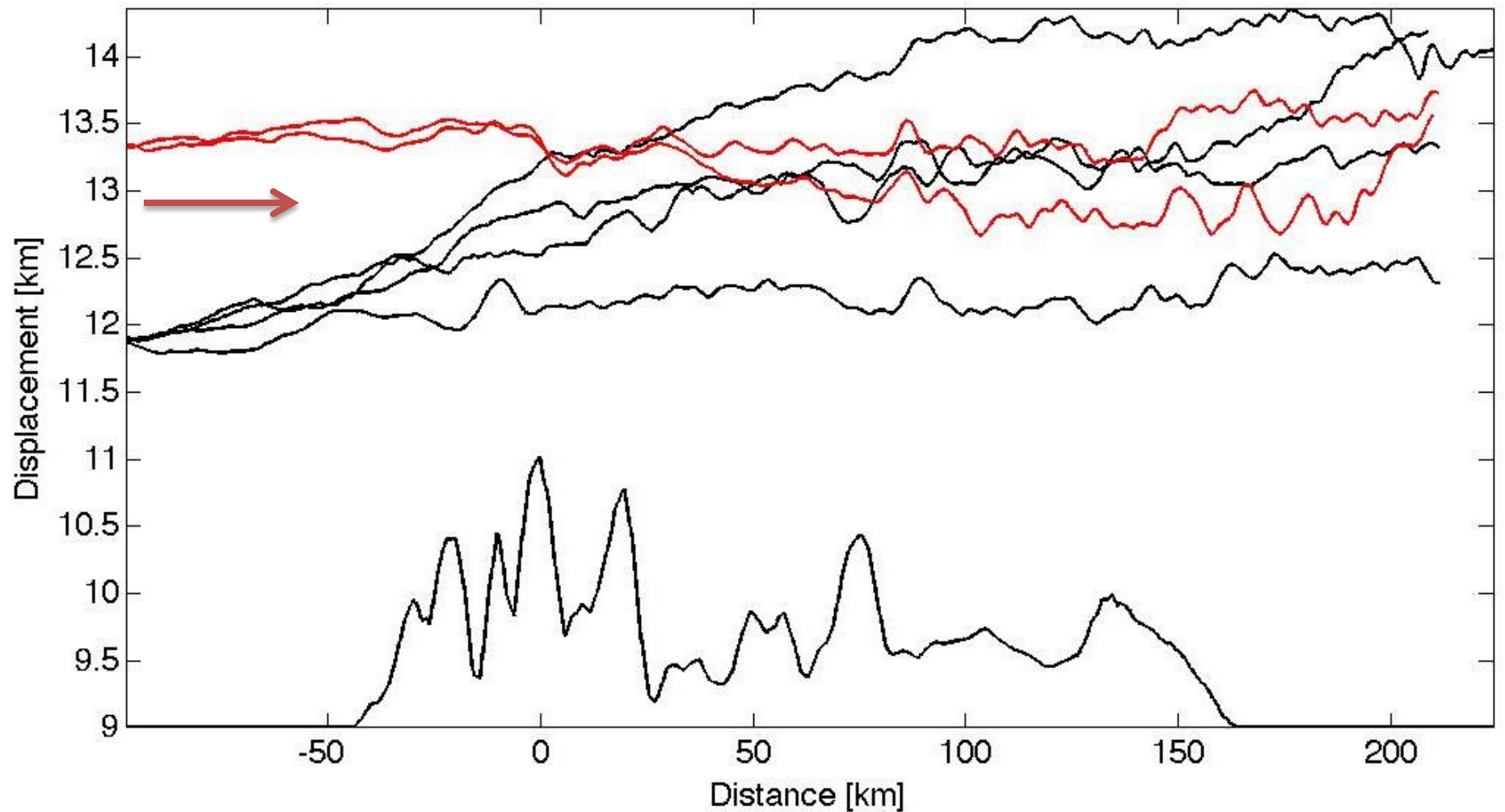
RF012: 5 legs over Mt Cook

Vertical displacement



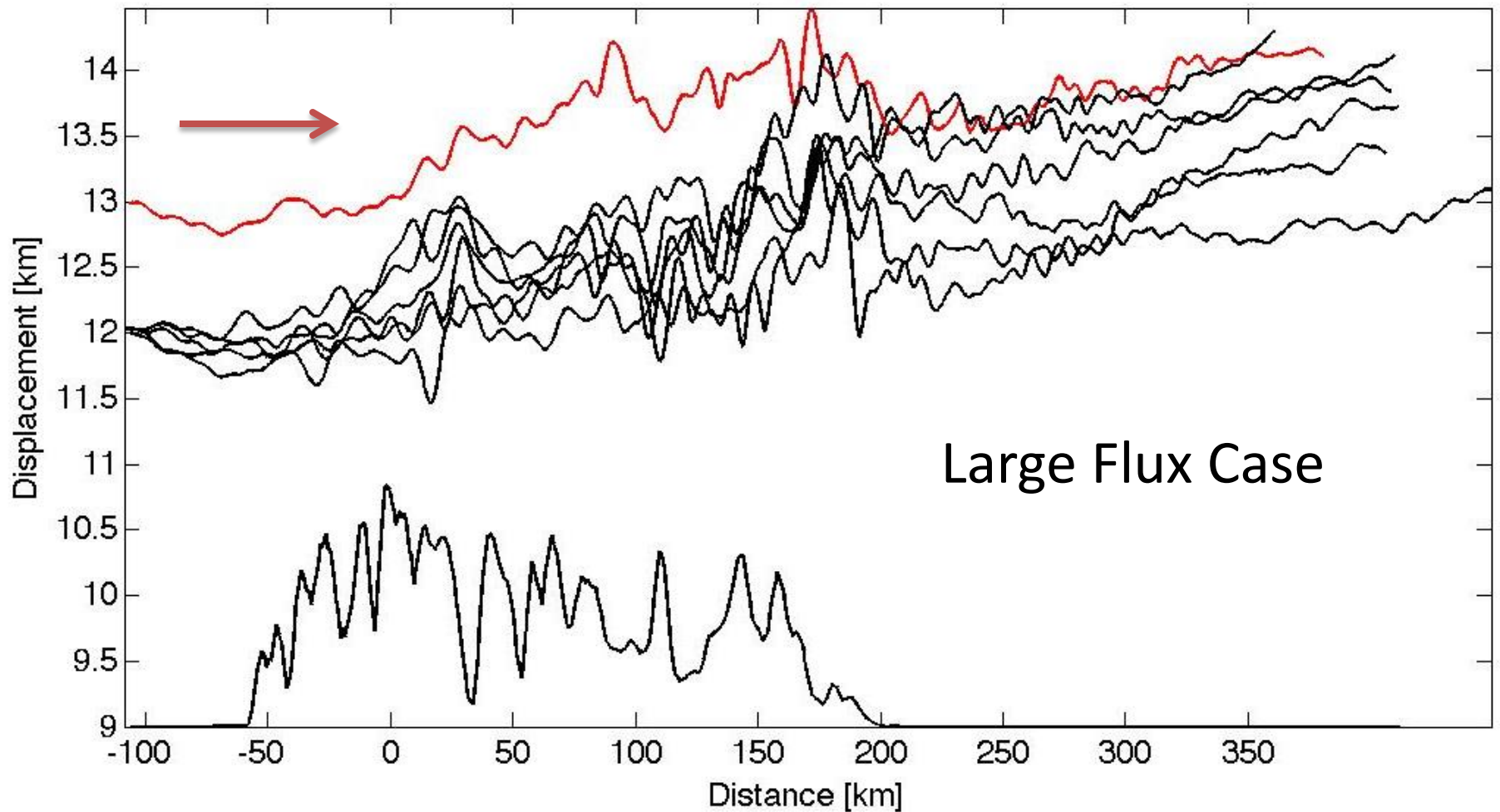
RF13: 6 Legs over Mt Aspiring

Vertical displacement



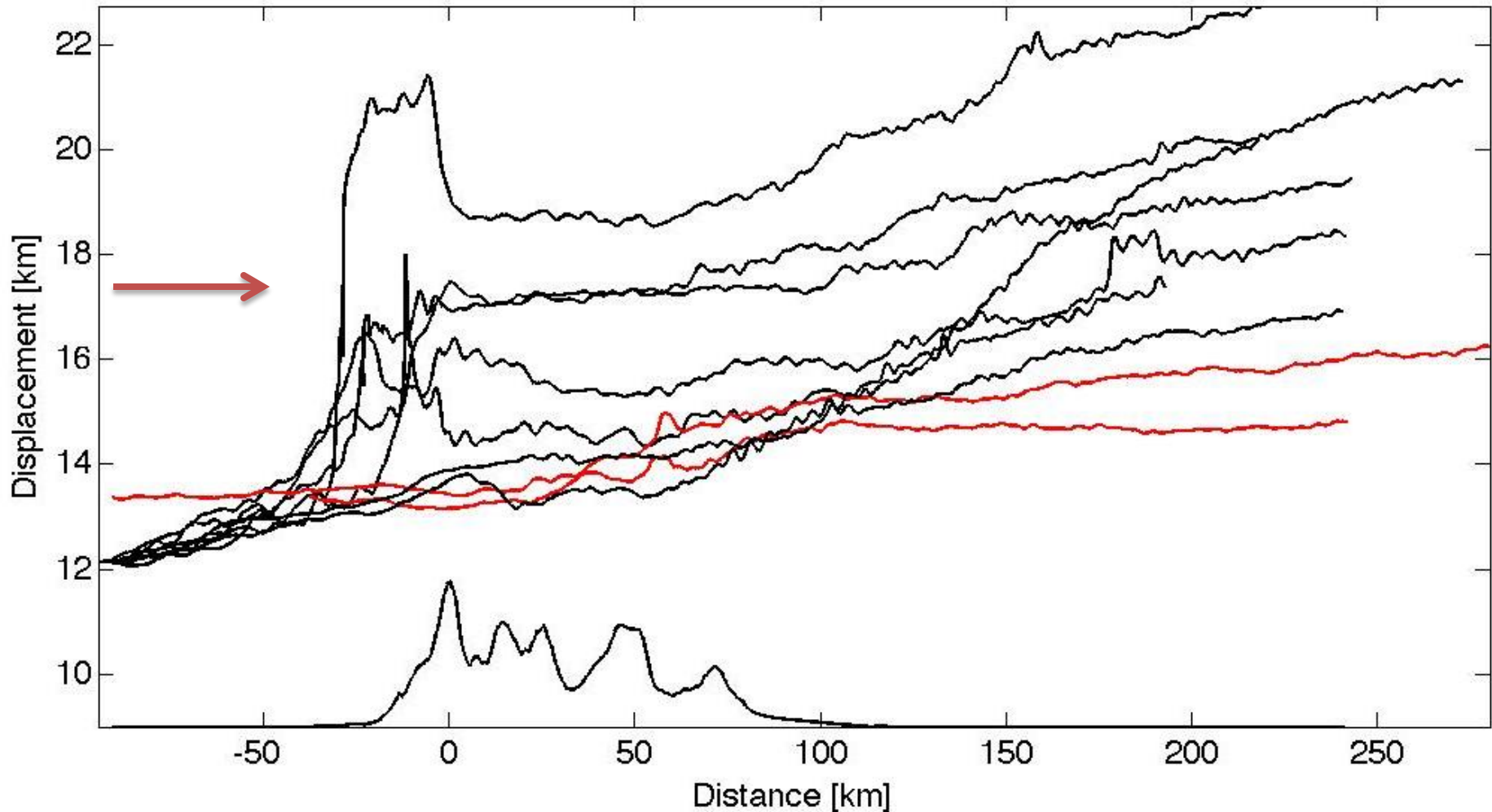
RF16: 7 Legs over Mt Aspiring

Vertical displacement



RF21: 9 Legs over Mt Cook

Vertical displacement



Flux calculations

The fluxes are computed from

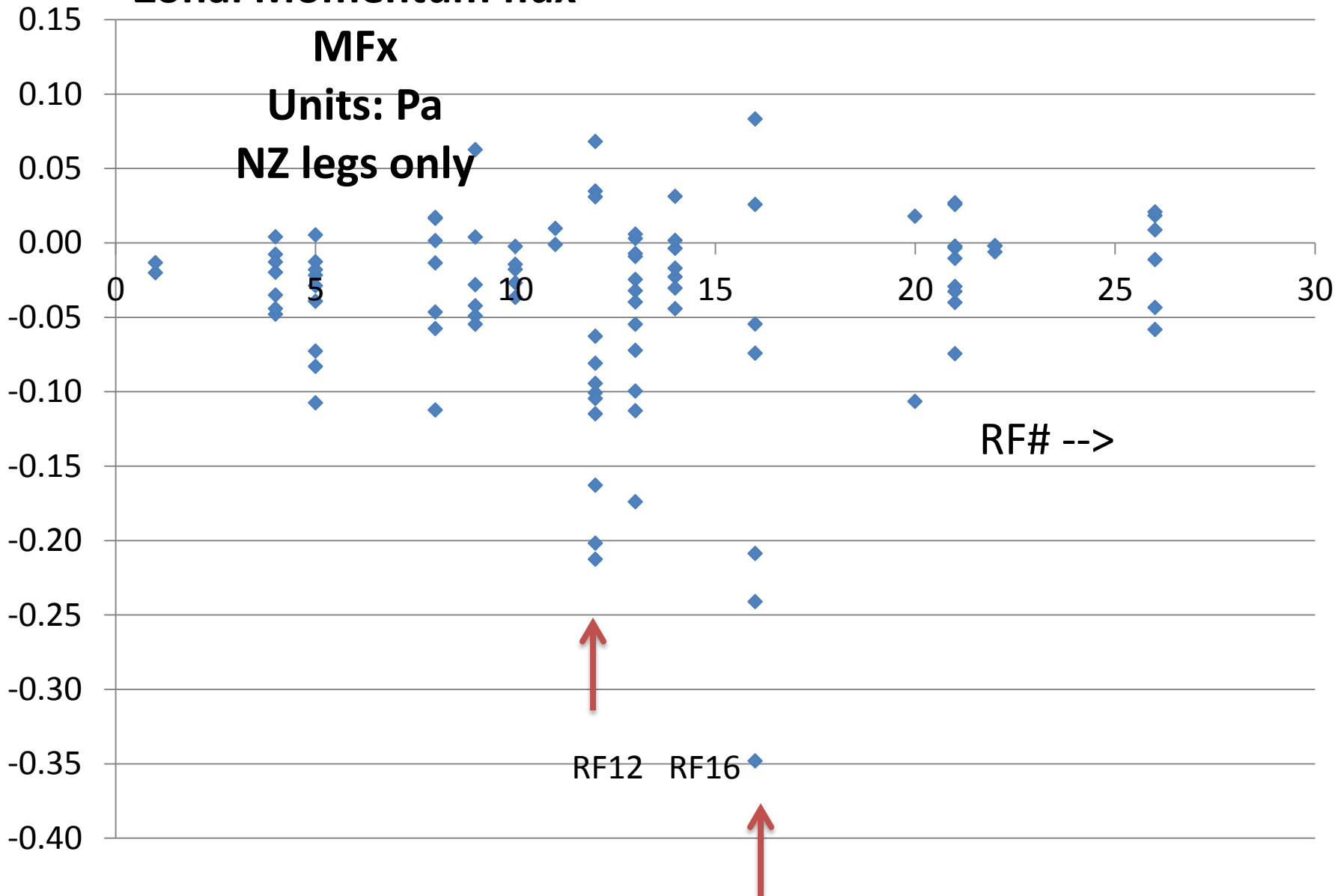
- $MF_x = \bar{\rho} \langle u' w' \rangle$
- $MF_y = \bar{\rho} \langle v' w' \rangle$
- $EF_z = \langle P_{cg} w' \rangle$
- $EF_x = \langle P_{cg} u' \rangle$
- $EF_y = \langle P_{cg} v' \rangle$
- $EF_z M = -(U^* MF_x + V^* MF_y)$

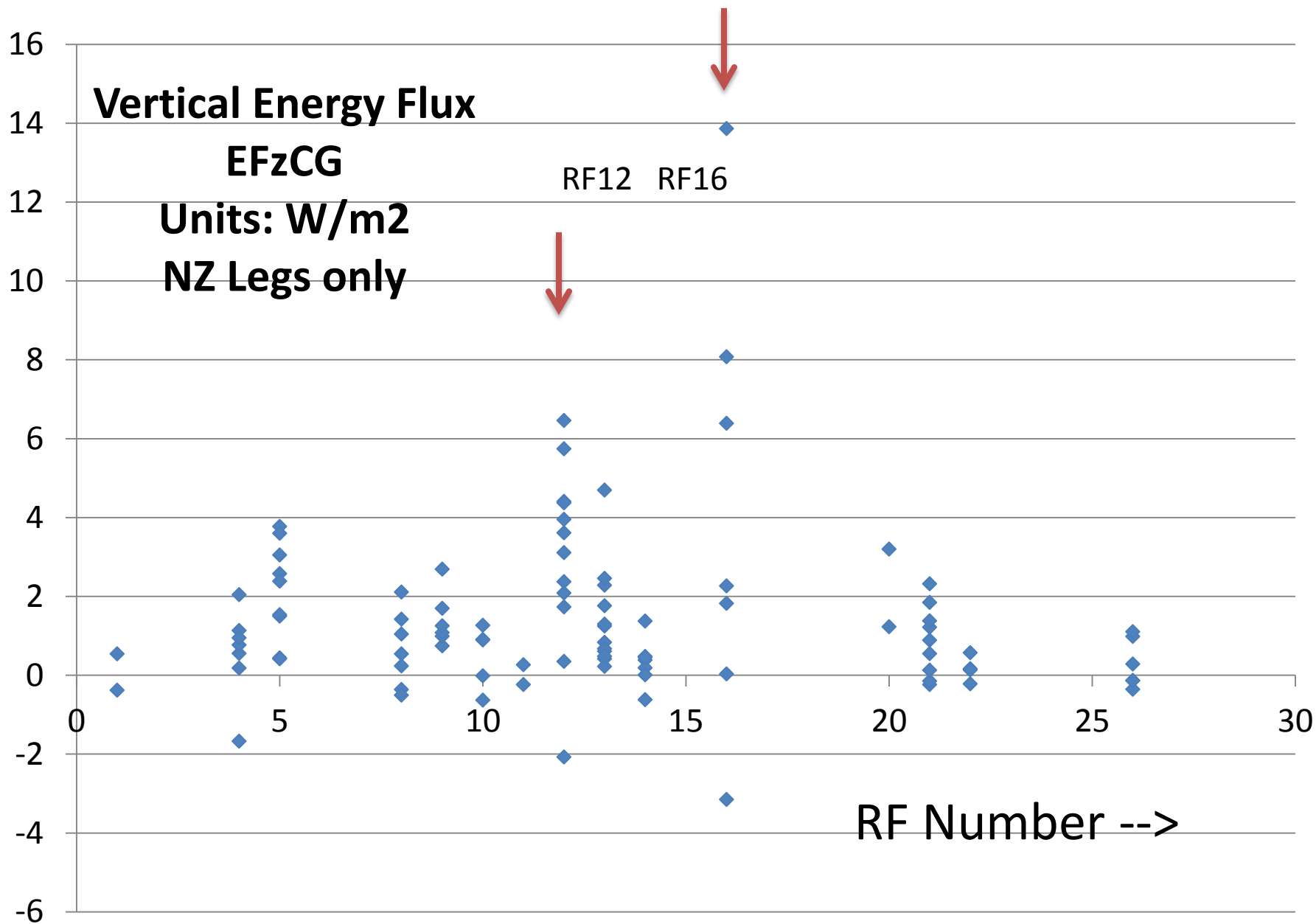
Zonal Momentum flux

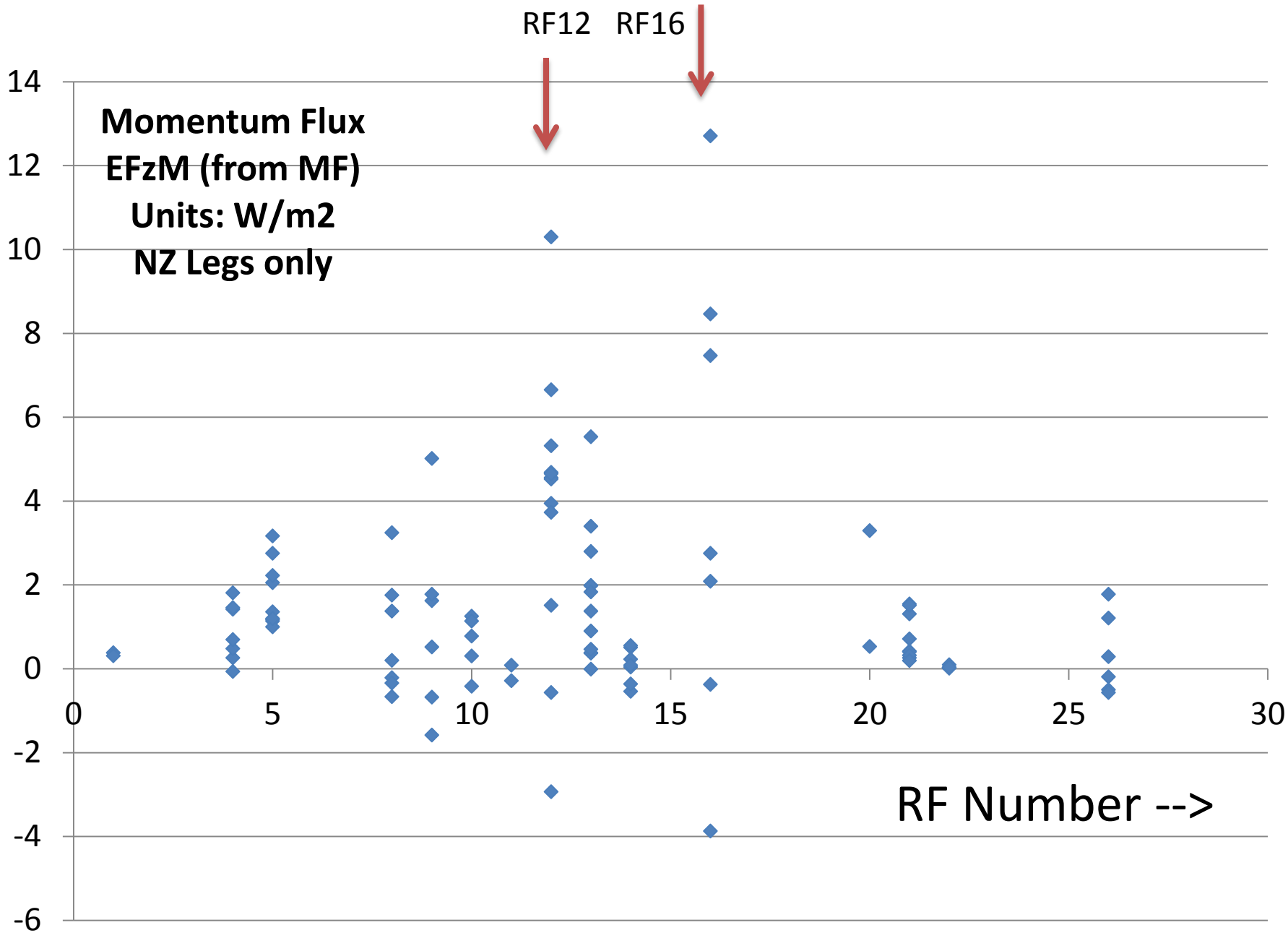
MFx

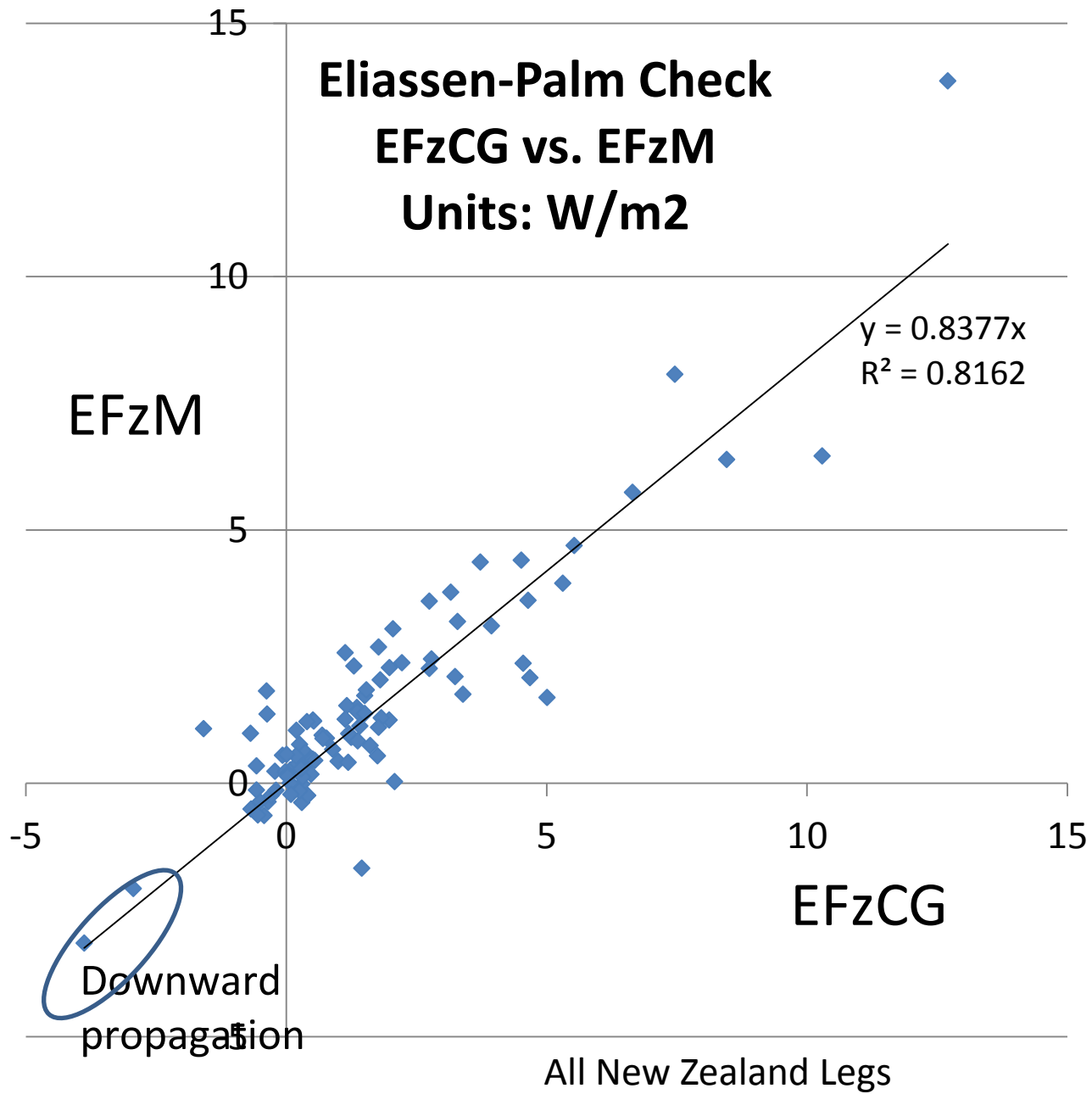
Units: Pa

NZ legs only



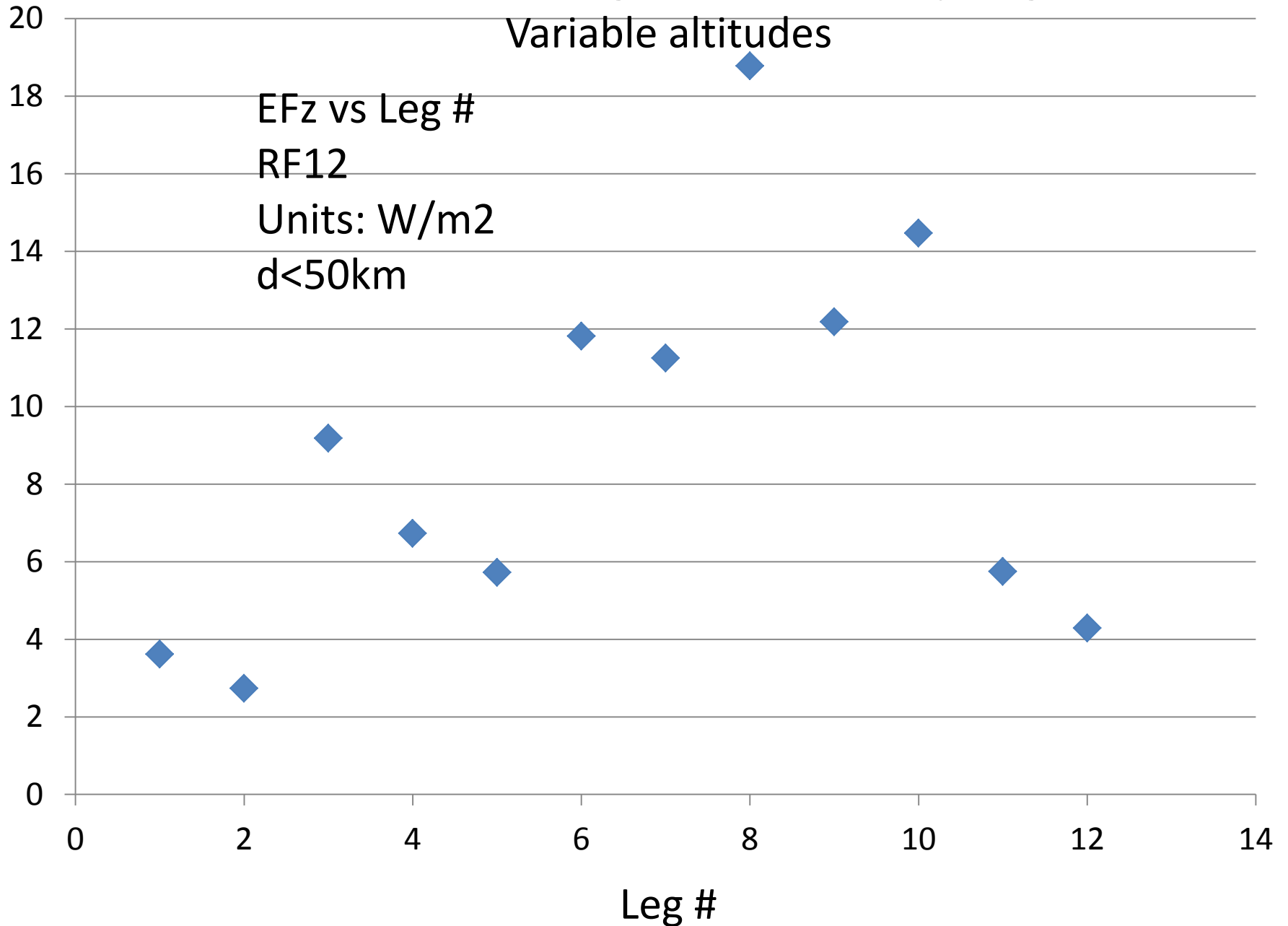


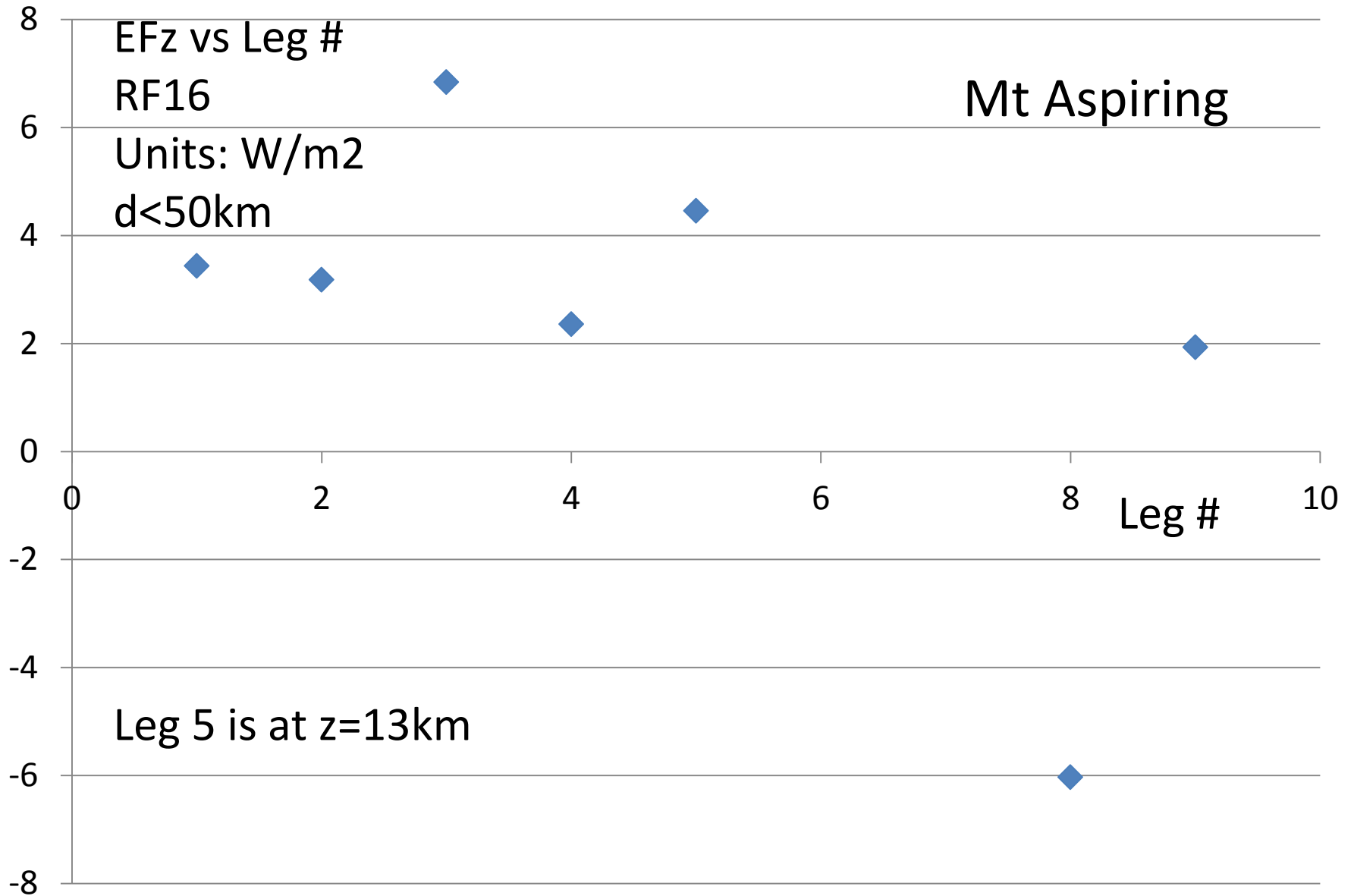




RF12: Alternating Mt Cook and Aspiring

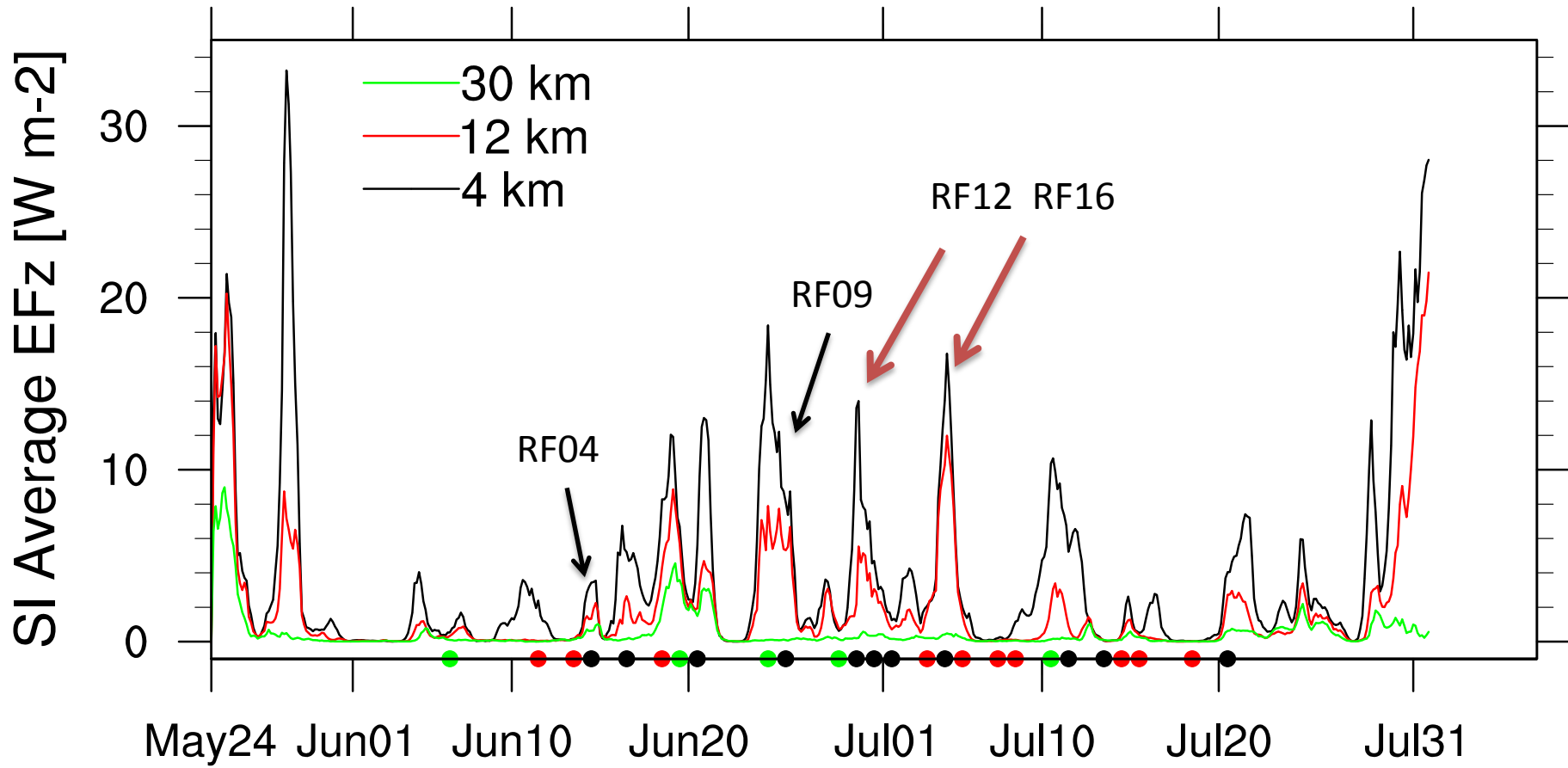
Variable altitudes





Yale WRF Long Run

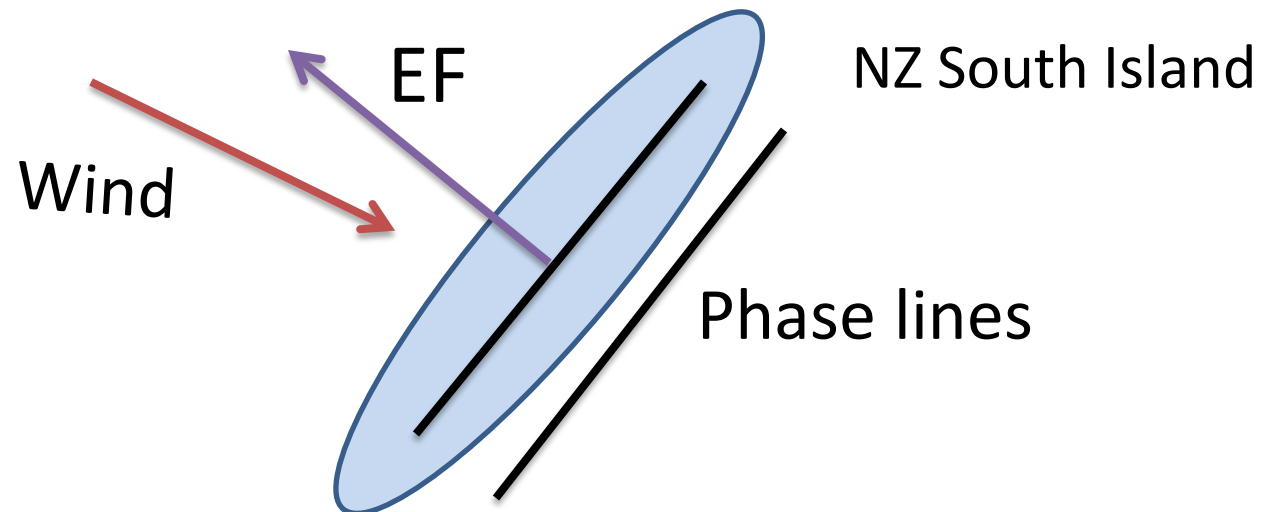
SI Averaged EFz



SI Flights !SI Flights Combination

Horizontal energy flux direction

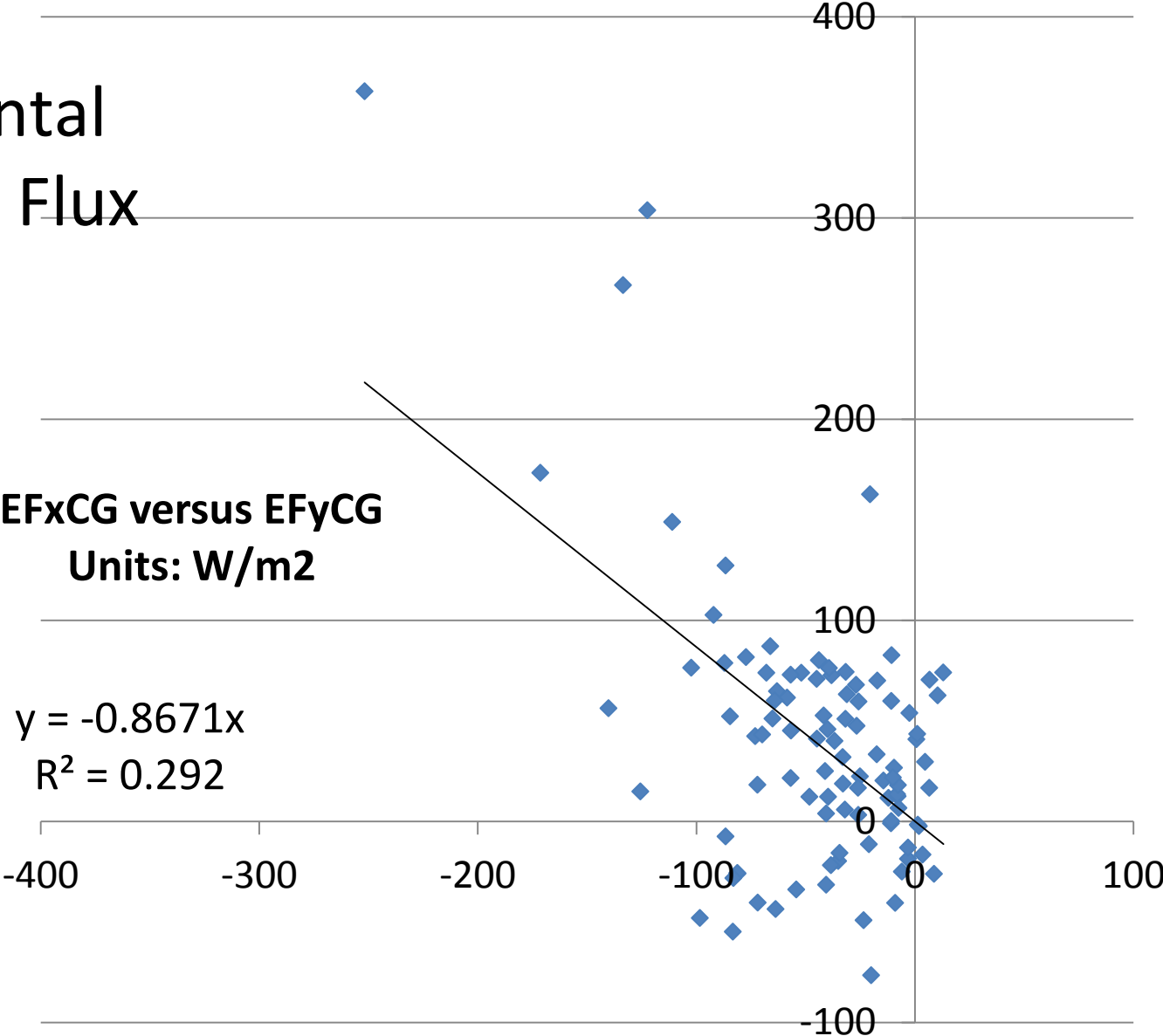
- The horizontal energy flux (E_{Fx} , E_{Fy}) vectors should be acting against the mean flow .



Horizontal Energy Flux

EFxCG versus EFyCG
Units: W/m2

$y = -0.8671x$
 $R^2 = 0.292$



Pressure analysis

- Error analysis for EF
- Correcting for aircraft altitude and the Coriolis force
- Redundant static pressure

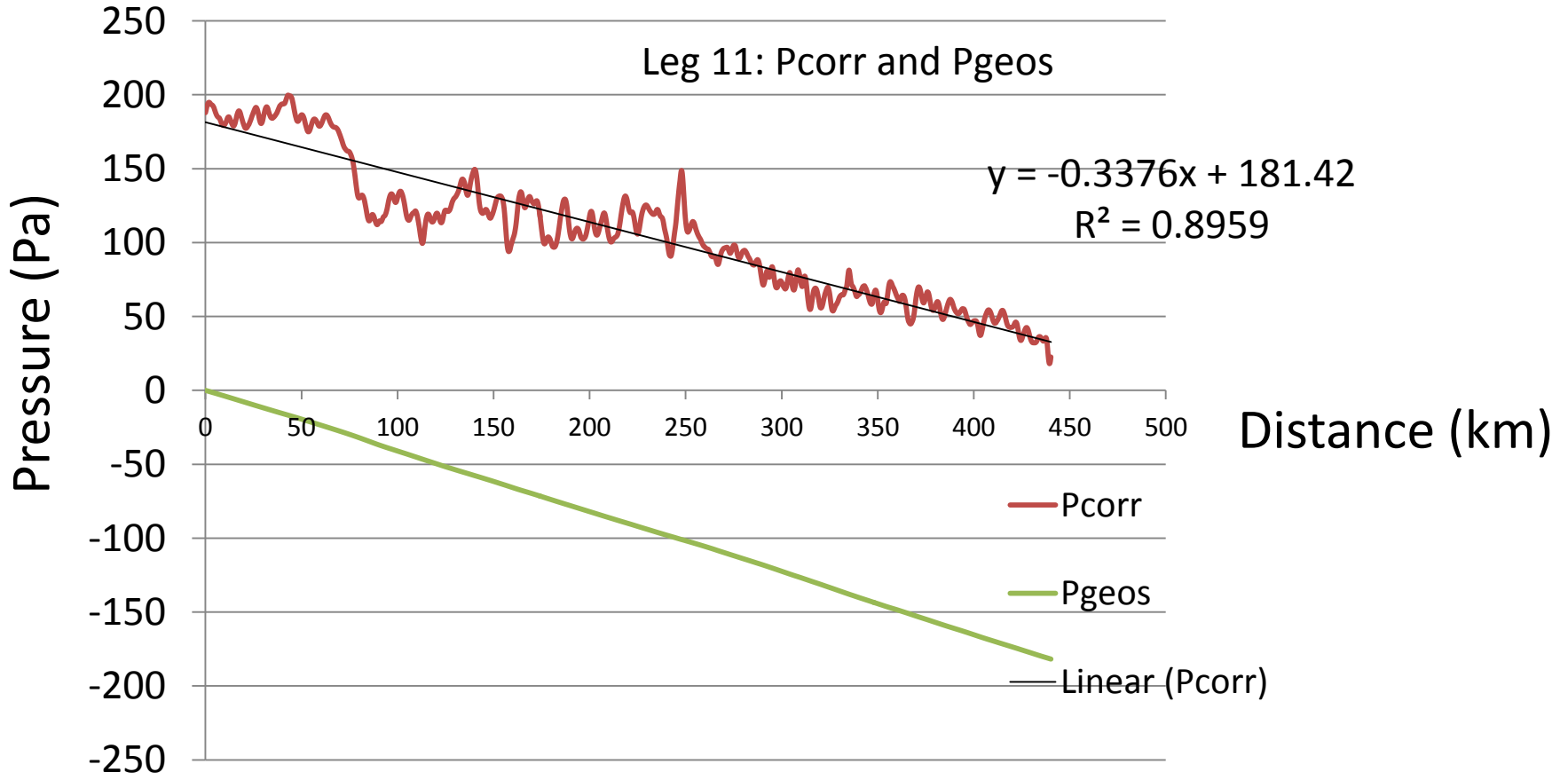
Error estimates for $EF_z = \langle p'w' \rangle$

- Assume a reference case with $w' = 1 \text{ m/s}$ and $p' = 10 \text{ Pa}$ so $EF_z = 10 \text{ W/m}^2$
- A typical error in P_{static} is $p' = 0.1 \text{ hPa} = 10 \text{ Pa}$
 - (100% error in EF_z)
- A typical error in altitude is 1 meter, giving a pressure error of $(0.31)(9.81)(1) = 3 \text{ Pa}$
 - (30% error in EF_z)
- A typical error in W is 0.2 m/s .
 - (20% error in EF_z)

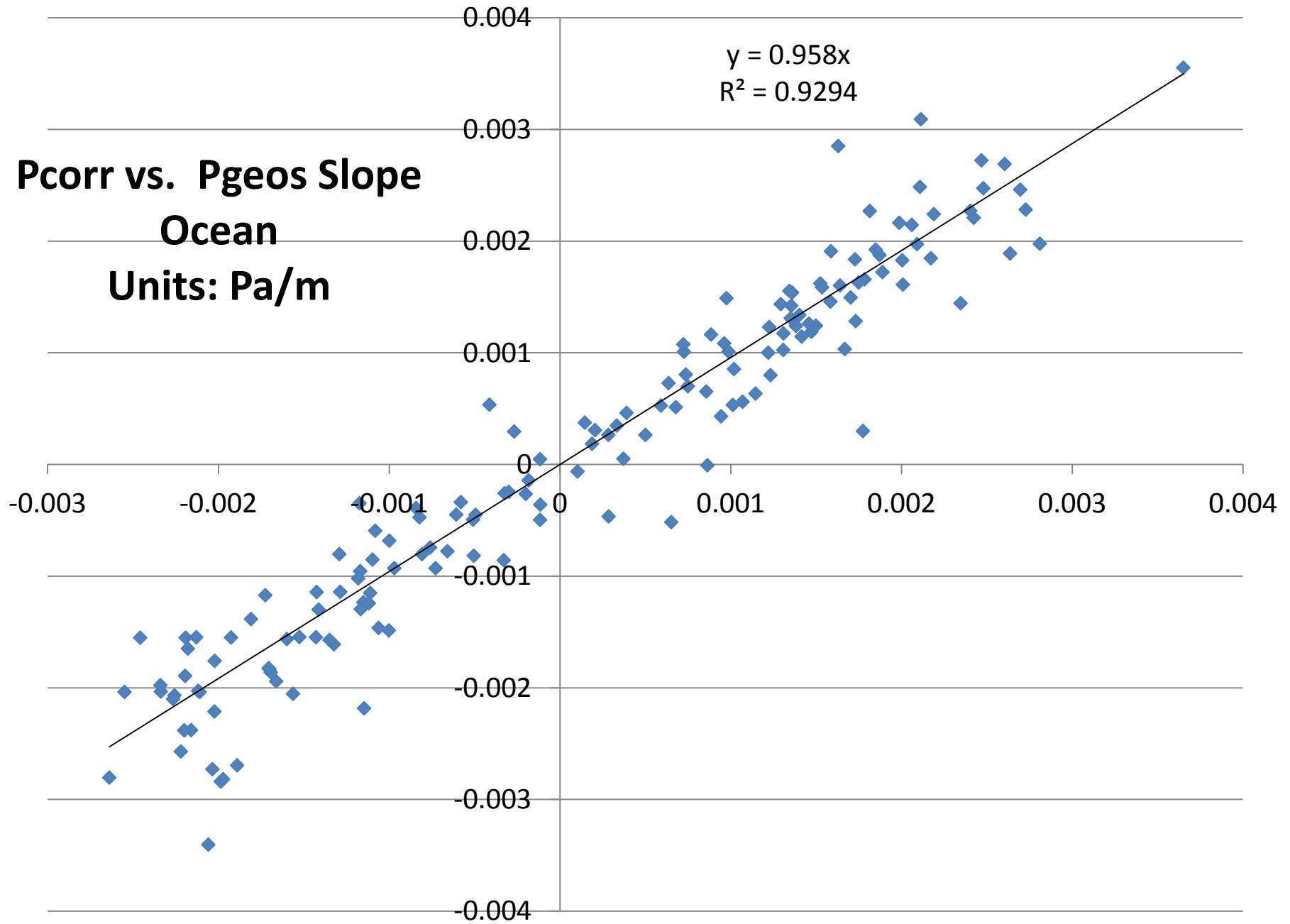
Corrected pressure

- P_{static} is fuselage static pressure corrected for airflow effects
- P_{cg} is the static pressure, corrected for altitude fluctuation and the geostrophic pressure gradient
- $P_{corr}(x) = P_{static}' + \bar{\rho}g(GGalt')$
- $P_{GEOS}(x) = \bar{\rho}2(0.0000727) \int_0^x \sin(\varphi) U_{CT} dx$
- $P_{cg}(x) = P_{corr}(x) - P_{GOES}(x)$

RF04 Leg 11



Pcorr vs. Pgeos Slope
Ocean
Units: Pa/m

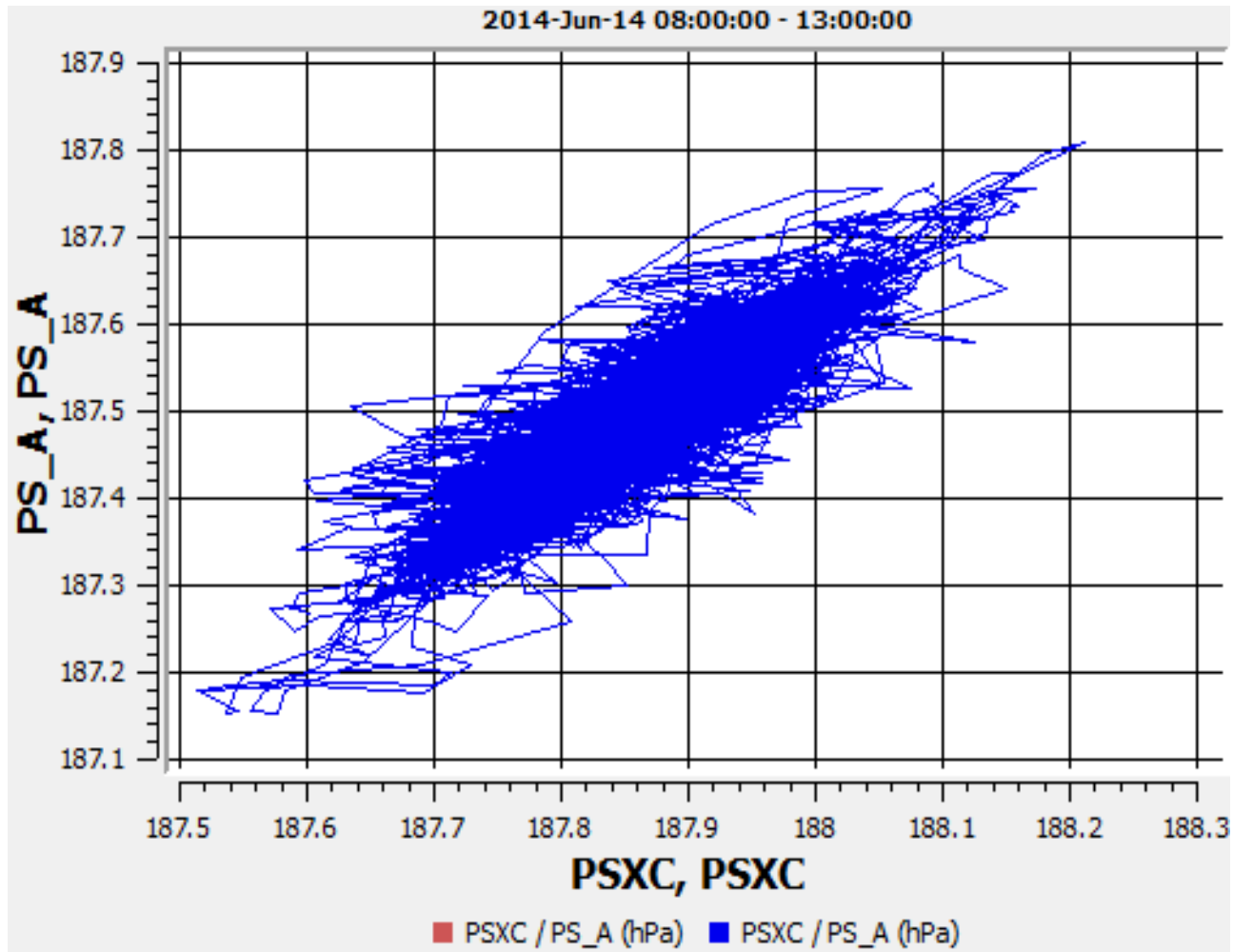


Instrument Redundancy

- In the Preliminary Deepwave data set, the only useful redundant measurement is static pressure (PSXC and PS_A).
- In the final data set, with the gust pod recalibrated, we hope to have an additional u,v,w,p data set and a new DGPS data set for two flights

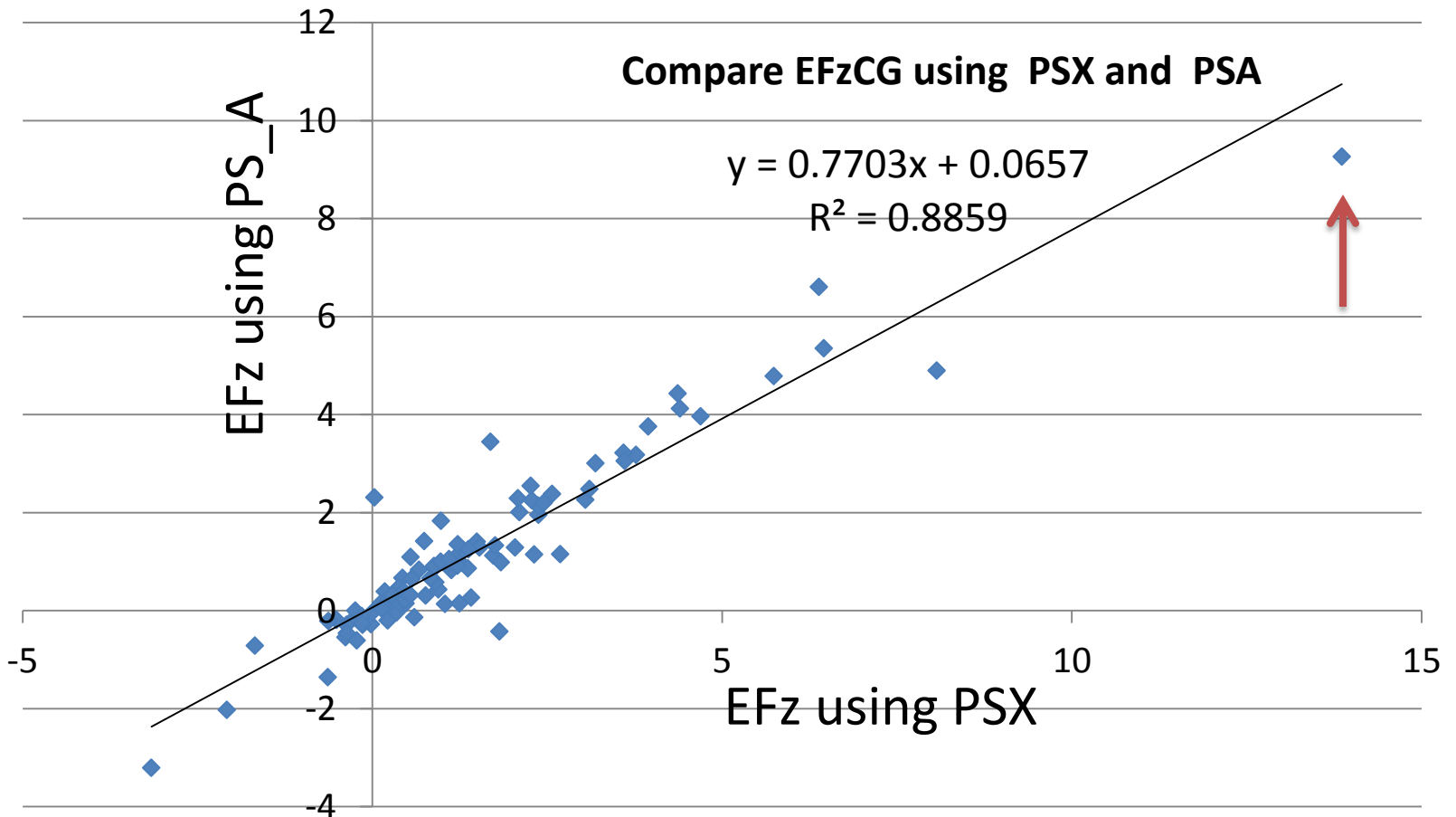
Redundant static pressure (RF04)

Uncertainty=10Pa

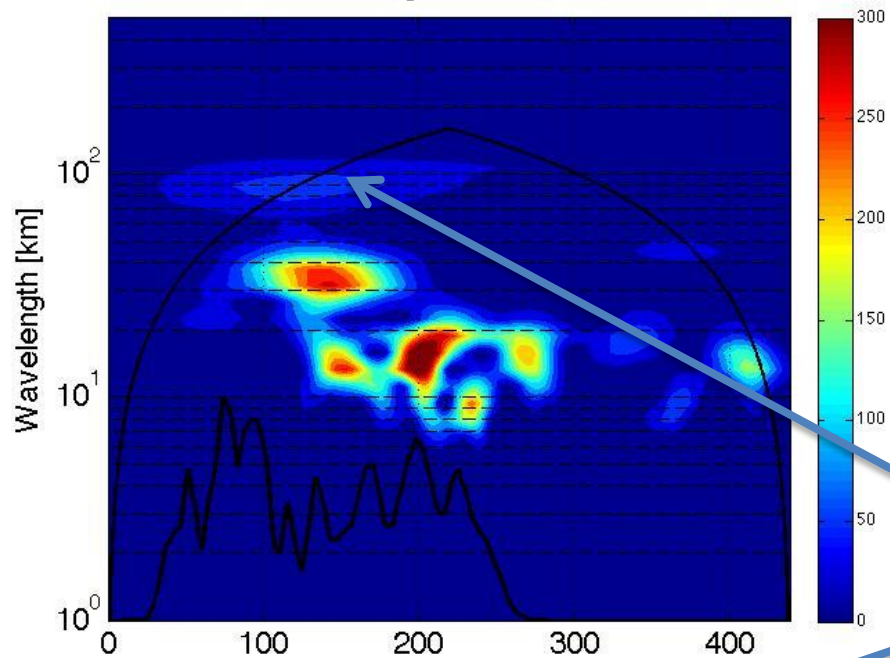


Vertical Energy flux:

two different pressure sensors (PSX and PS_A)



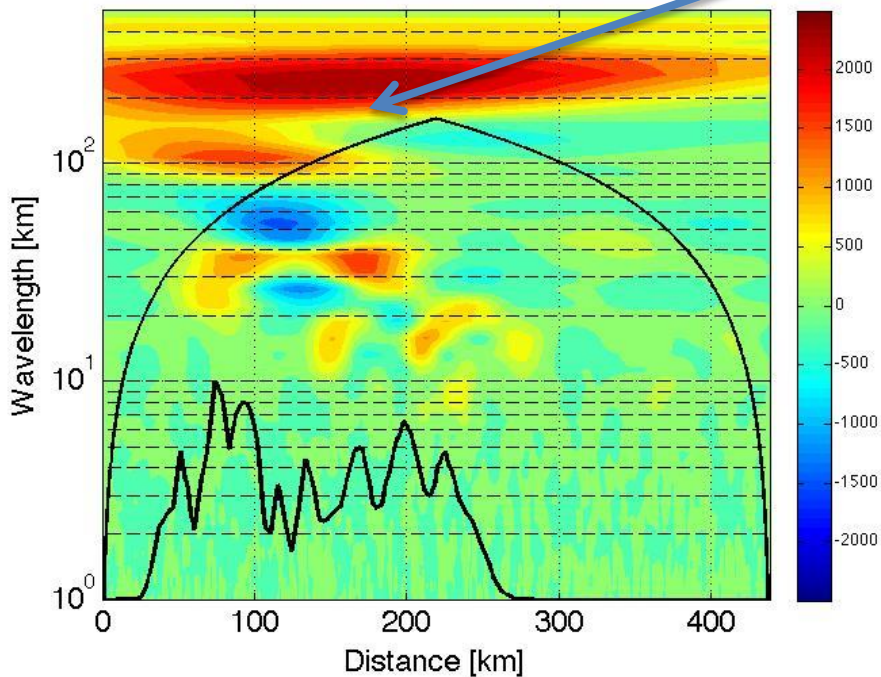
RF4 Leg 3 W Power



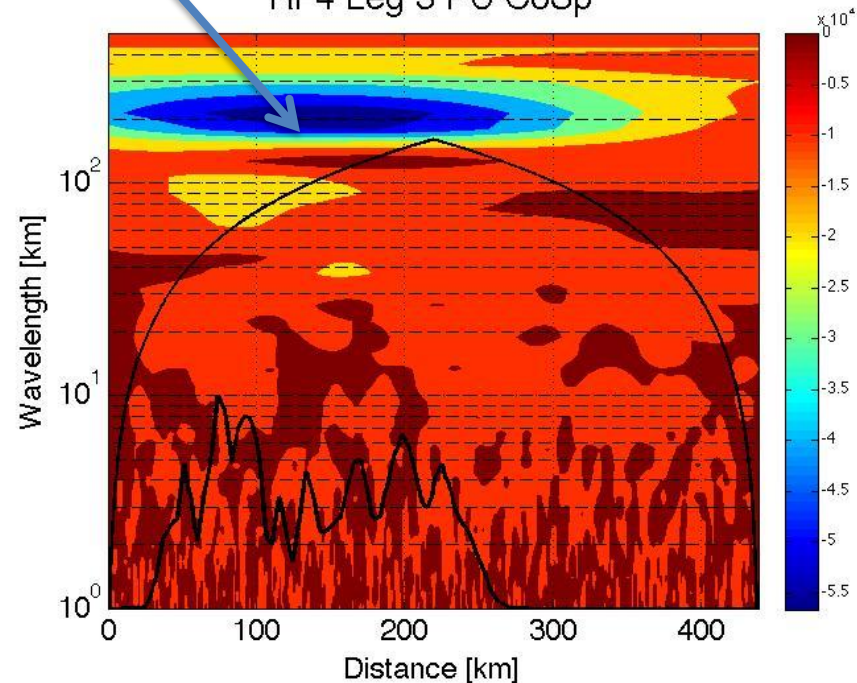
Wavelet Scale
Analysis of
RF04; Leg 3
@z=12.2km

Flux-carrying Waves

RF4 Leg 3 PW CoSp

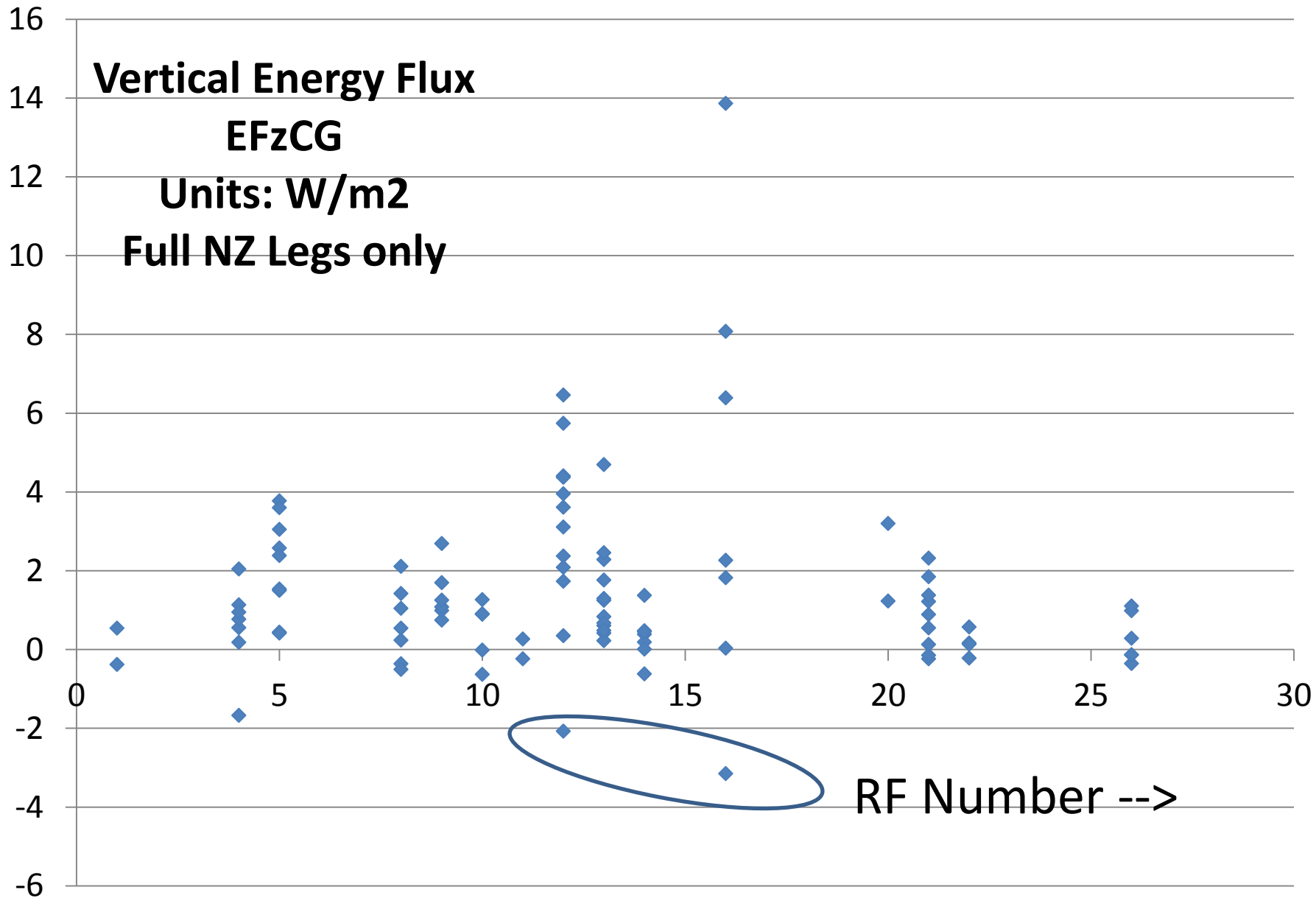


RF4 Leg 3 PU CoSp

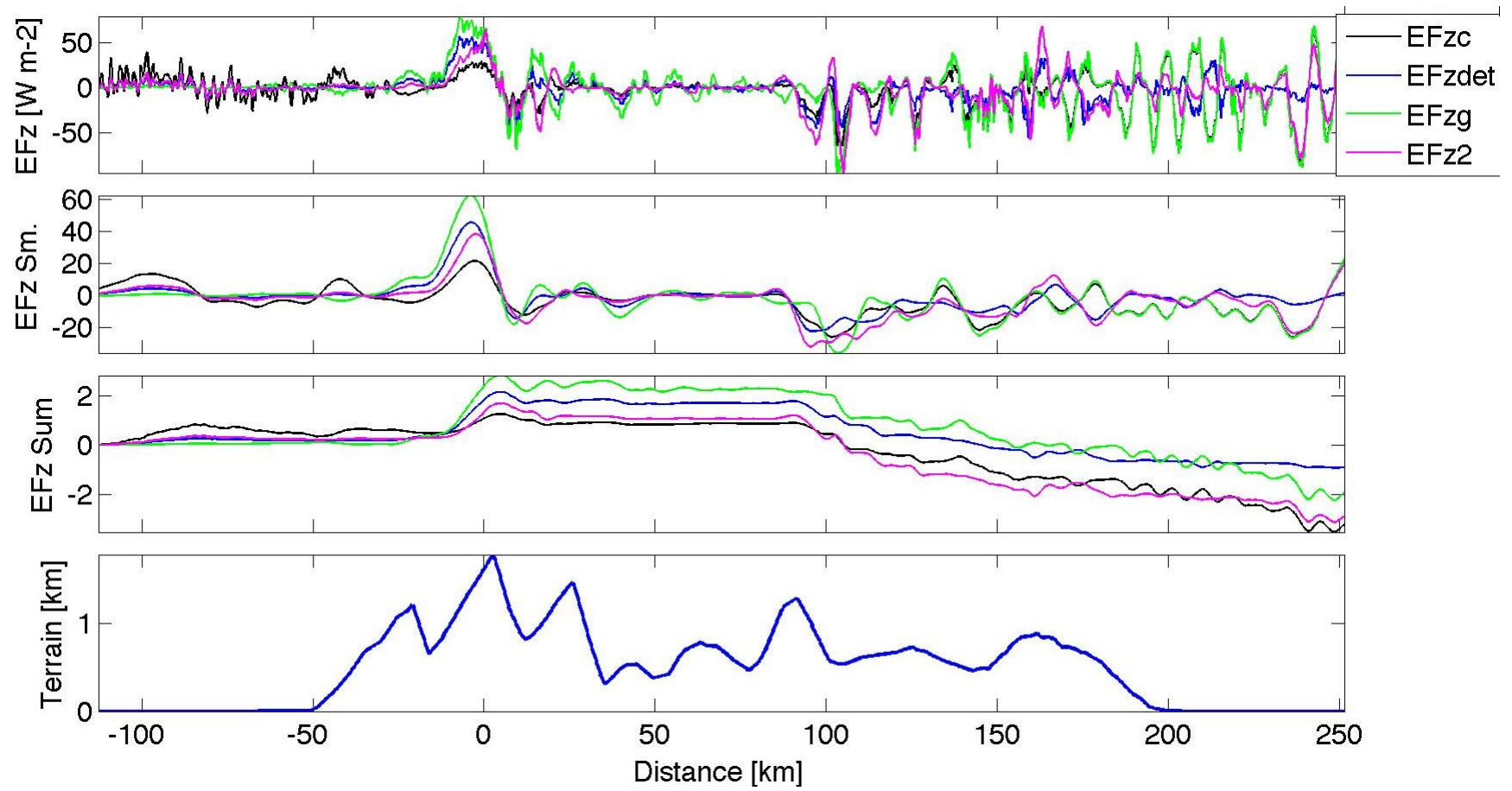


Negative Energy Flux EF_z

- A few legs with negative EF_z are seen
- These fluxes still fall on the E-P line
- Mostly caused by downward wave beams over the east end of Mt Aspiring

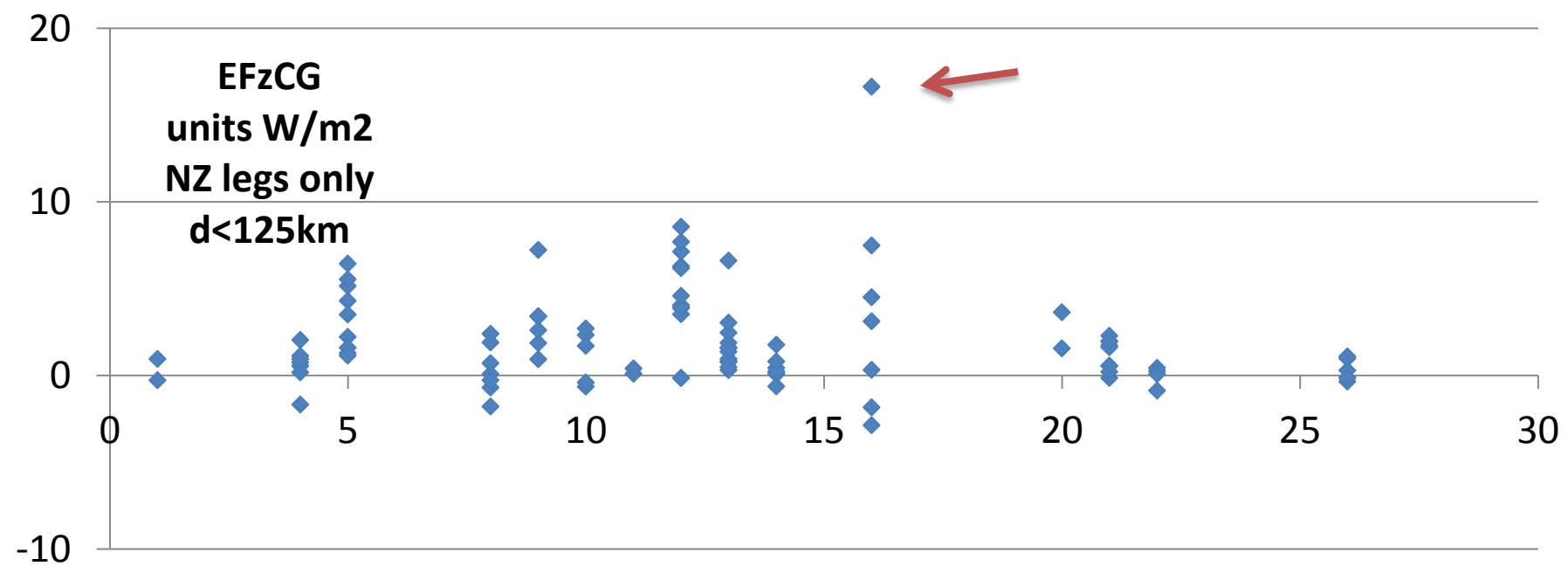
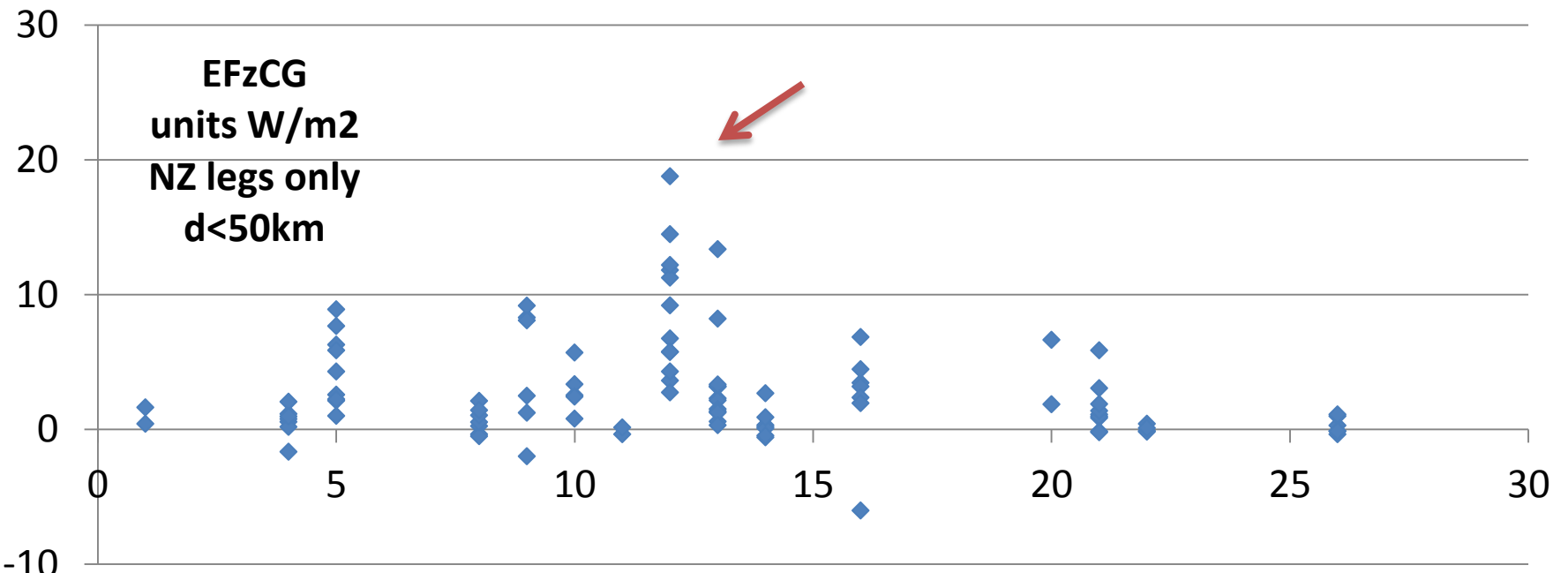


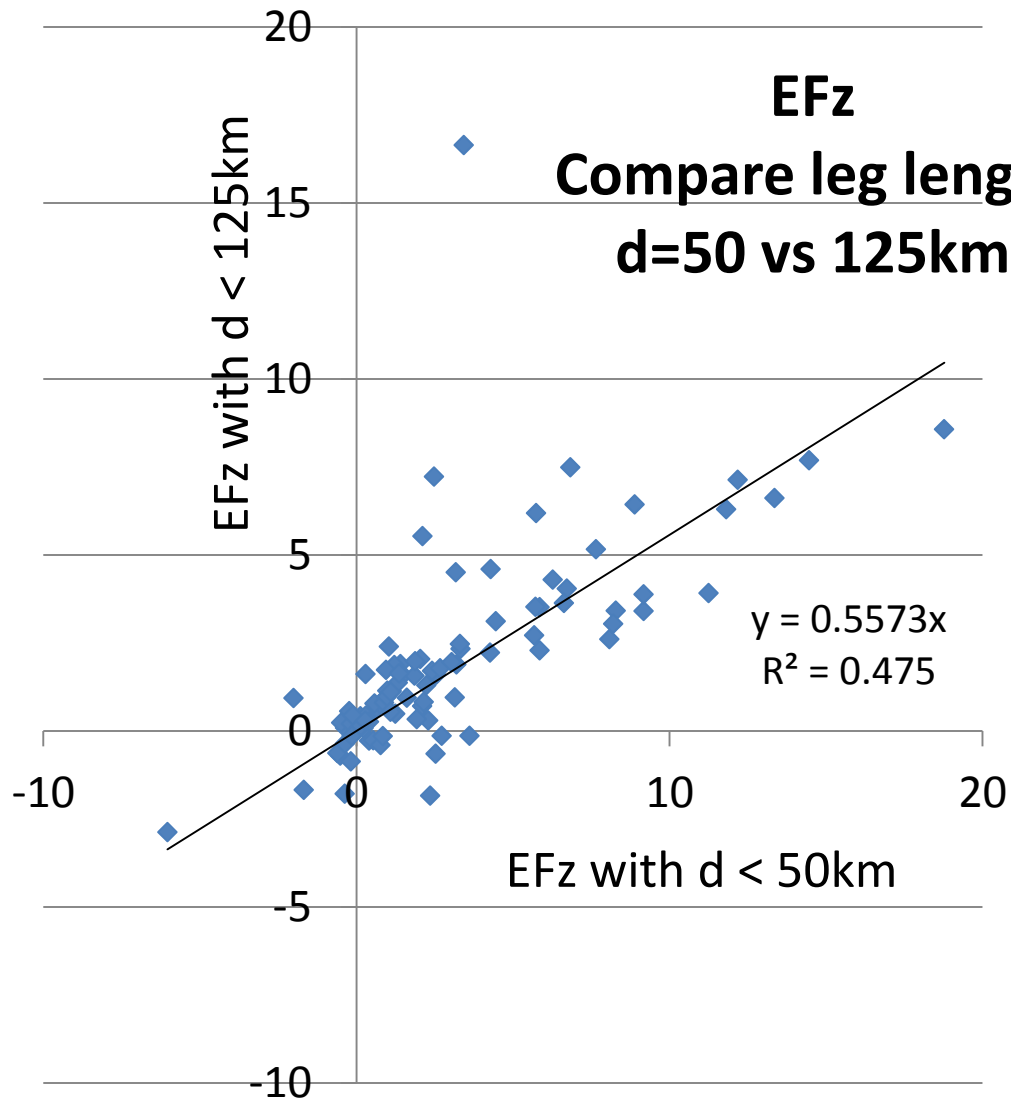
RF12 Leg 1: $EFz \sim -3W/m^2$



Sensitivity to leg length

- Compute fluxes only for distance from mountain peak $< d$
- Compare $d=50\text{km}$ and $d=125\text{km}$
- Maximum flux legs change with d
- Average flux values are less on the longer legs





Conclusions I

- Energy and Momentum fluxes are very transient within flights. Strong wave days have the largest flux variance and reversed fluxes.
- Observed momentum and energy fluxes satisfy the Eliassen-Palm condition: $EF_z = EF_z M$.
- Energy fluxes are sensitive (e.g. +/-20%) to static pressure sensor error.

Conclusions II

- Horizontal energy flux direction is mostly NW-ward; upwind and perpendicular to the NZ terrain.
- Almost every case has vertical velocities dominated by short waves with wavelength from 8 to 12km. These waves carry little flux.
- Dominant flux-carrying waves have wavelength from 70 to 250km

Conclusions III

- Flux values are sensitive to leg length. Flux density is greatest near the mountain peaks. Average flux decreases with integration leg length.
- Aircraft flux measurements in Deepwave have uncertainties of 30% or larger due to:
 - Lack of redundant sensors (so far?)
 - Large Unsteadiness
 - Sensitivity to leg length

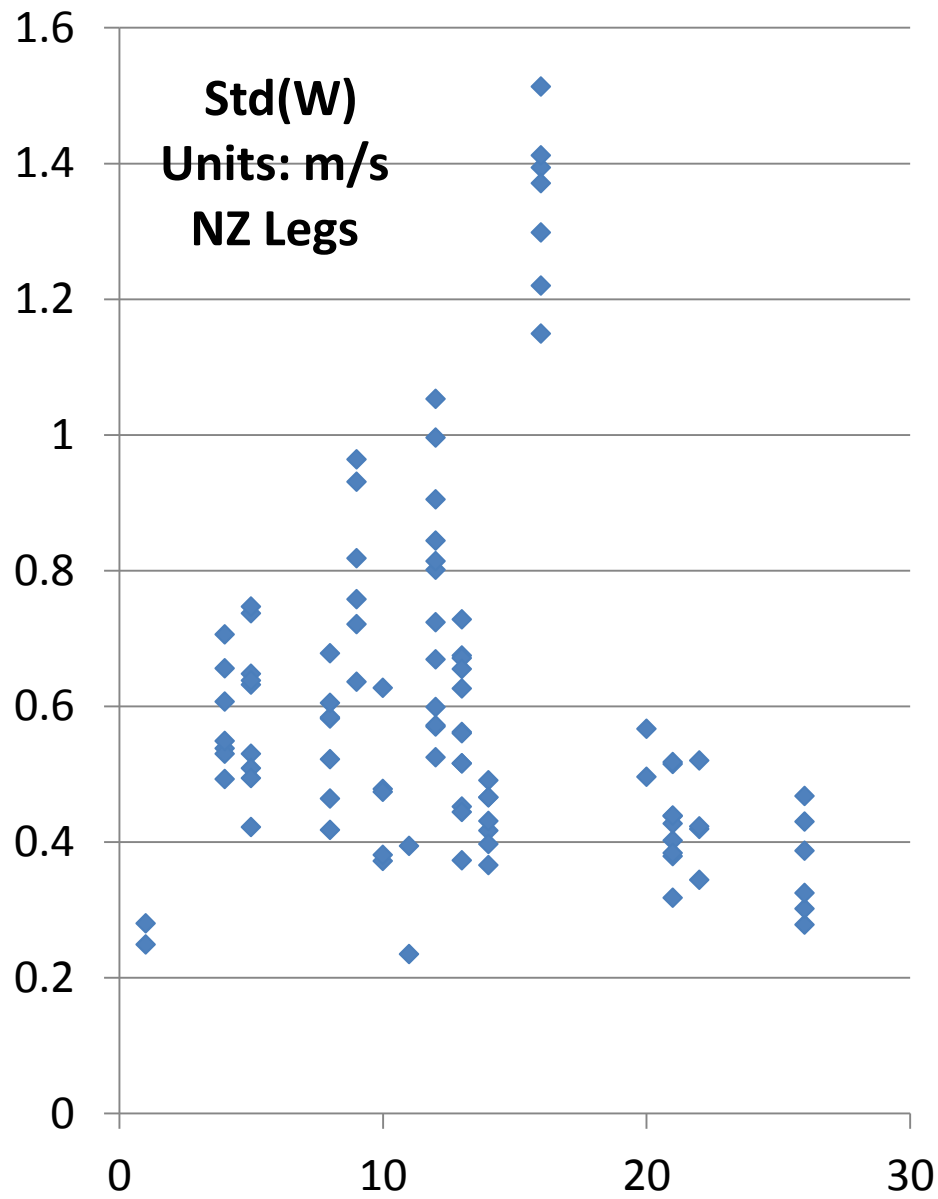
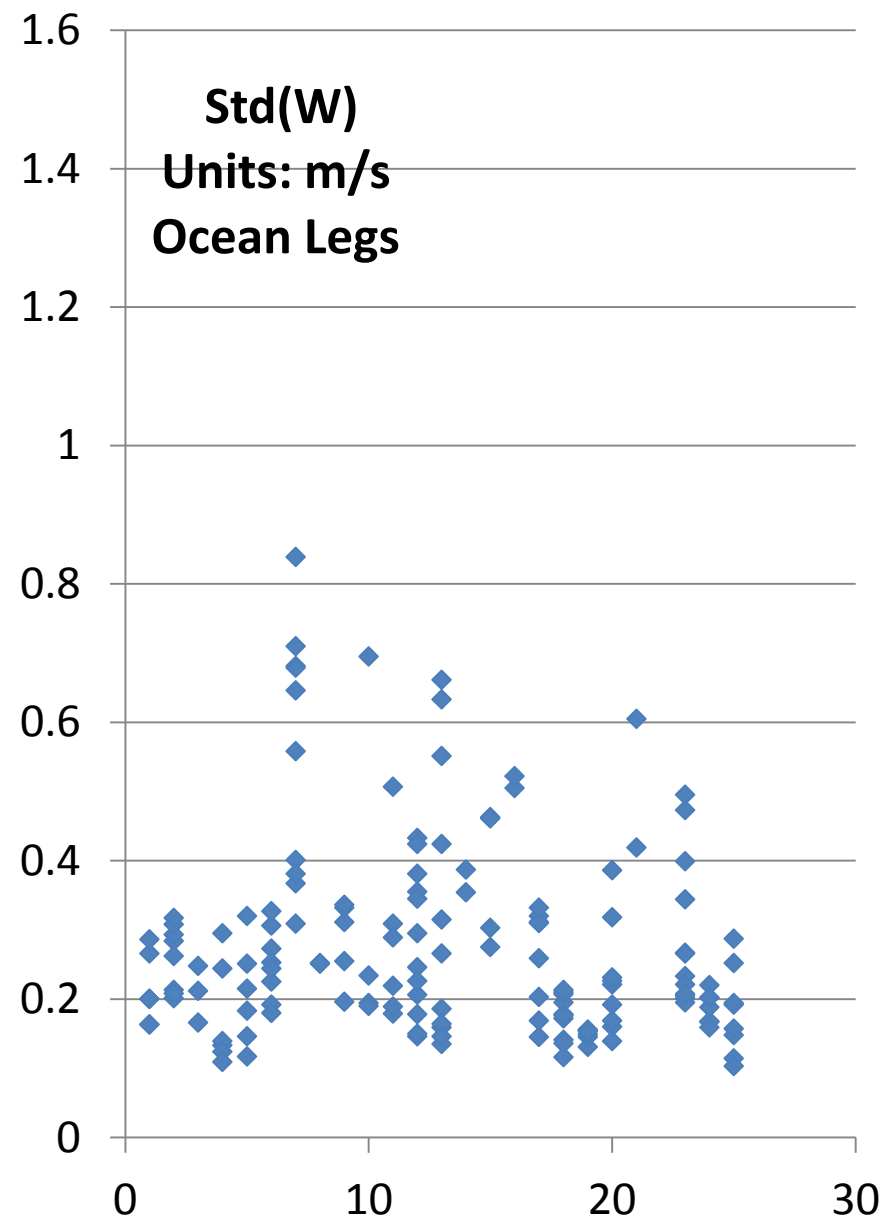
Yale Deepwave Priority Research

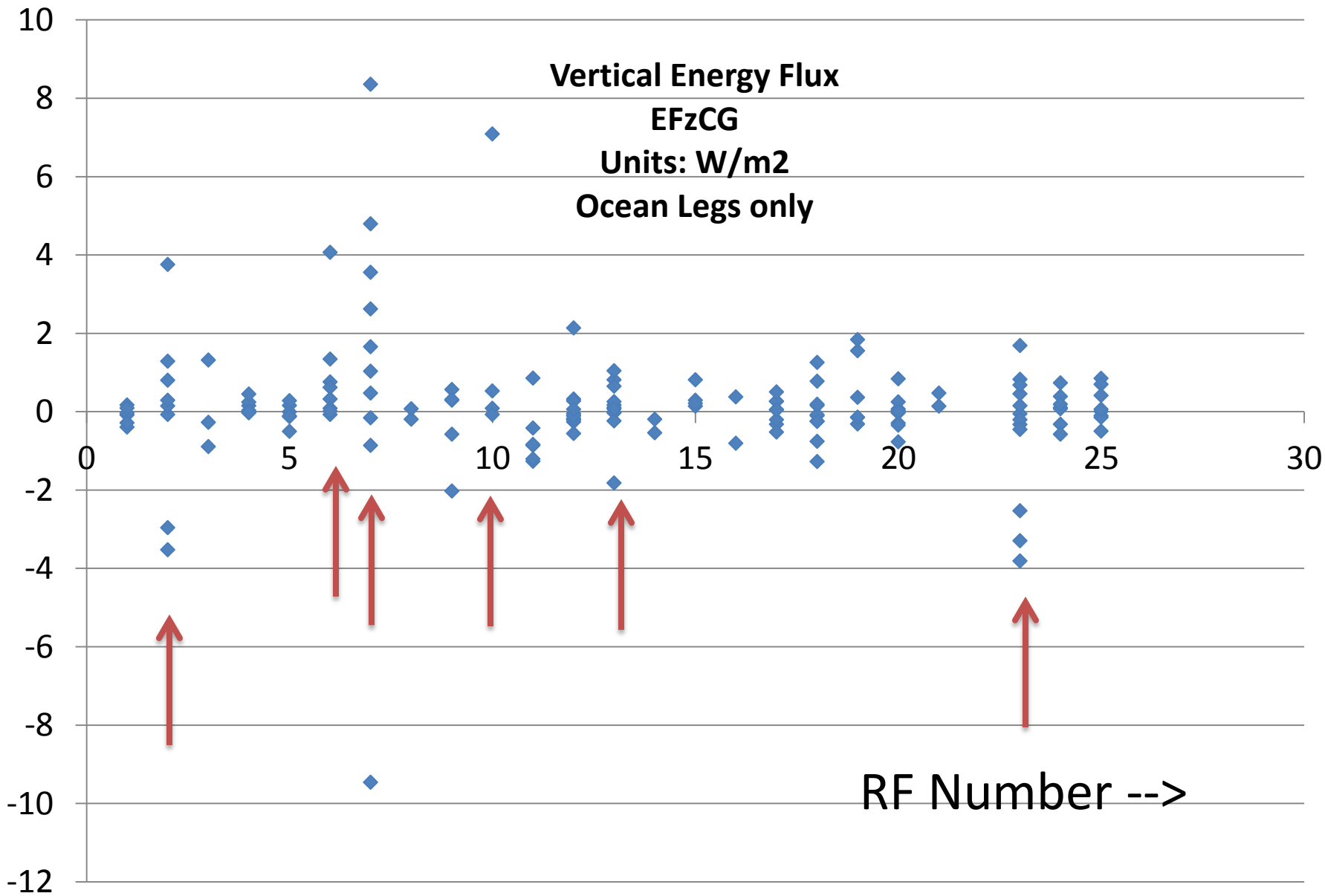
- Mountain wave transience
- Wave generation and the ABL
- Wave dissipation in the stratosphere
- Wave diagnostics from model output
- Flux error estimates, redundant measurements
- Trapped waves
- Moist processes; convection
- Downward propagating waves

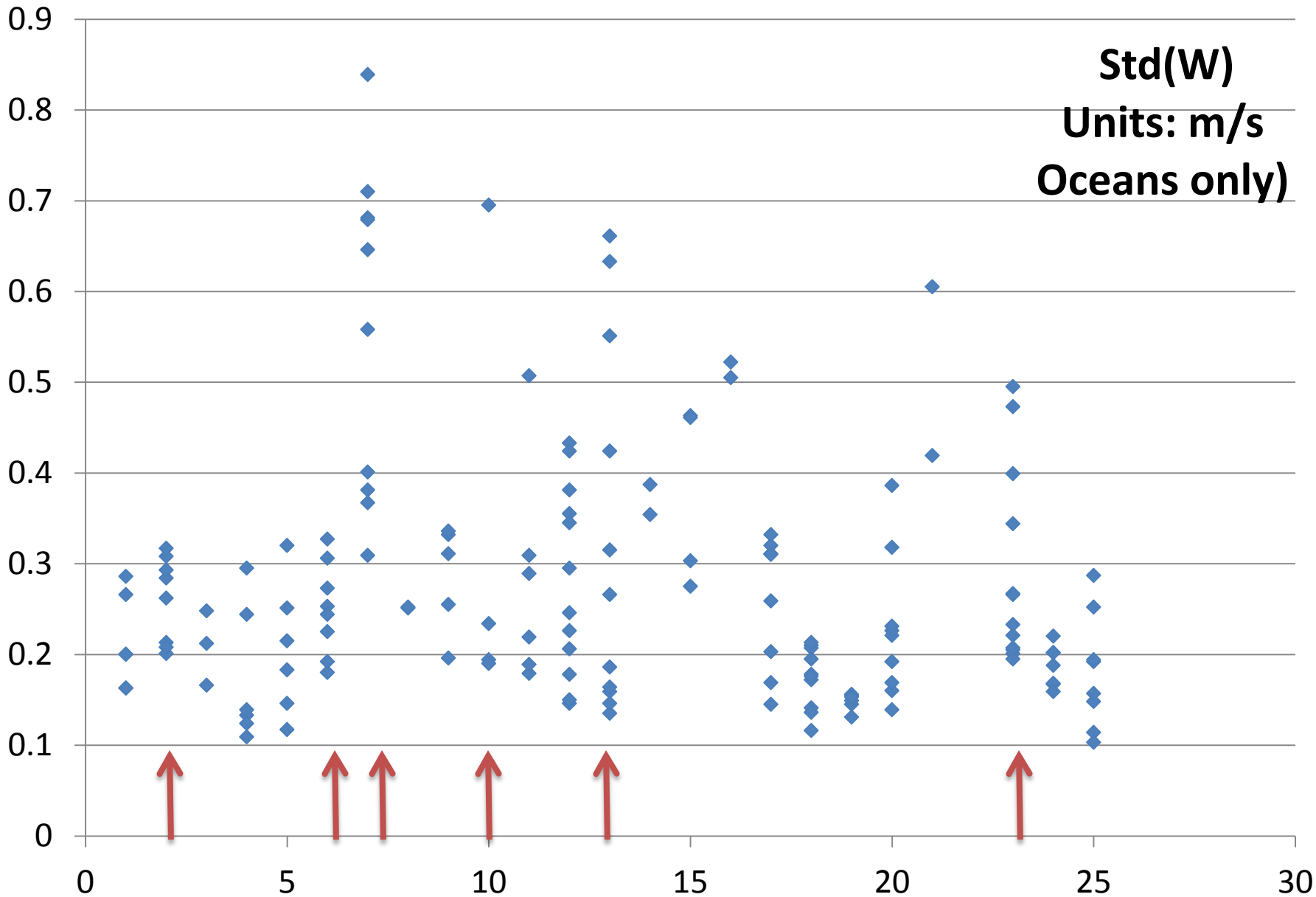
The End

Conclusions IV

- South Island area is approximately 160,000km², so $EF_z=10W/m^2$ gives 1.6 TeraWatts
- WRF and GV flux values are in rough agreement
- WRF-based deep cases on June 19-21
 - RF07: Not flown over NZ
 - RF08: Weak waves over Mt Aspiring







Significant “Ocean” vertical velocity or fluxes

- RF02: Tasmania
- RF06: Tasmania
- RF07: NZ box pattern (Bad WIC)
- RF10: Trailing wave leg near NZ
- RF13: Trailing wave leg near NZ
- RF23: Macquarie and Auckland Islands

Outline

- Deepwave GV flight level data set
- Momentum and Energy Flux statistics
- Pressure corrections for energy flux
 - Error analysis
 - The constant P assumption
 - Coriolis correction
 - Redundant pressure sensor
- Trapped waves and dominant scales
- Downgoing waves
- Effect of leg length
- WRF comparison
- Ocean versus NZ legs

Types of flux measurements

- Momentum flux
 - Traditional mountain wave quantity
 - Impacts large scale flow
 - Need gust-probe wind field only
 - Constant with height in steady, linear, non-dissipative flow
 - (not wave specific)
- Energy flux
 - New diagnostic quantity
 - Better physical interpretation in unsteady flows
 - Wave specific
 - (needs static pressure)

Motivations for flux measurements

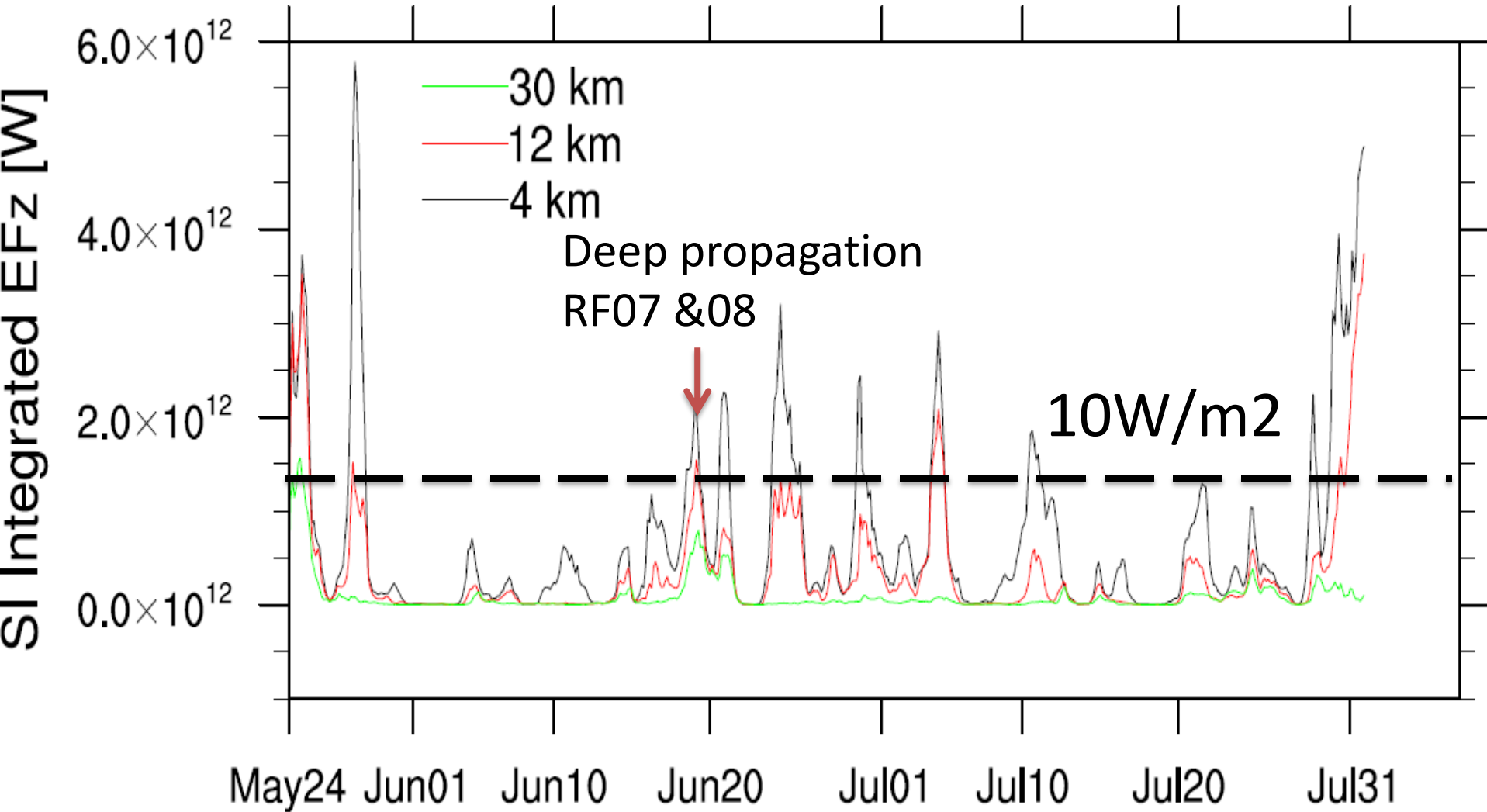
- Statistics for global models
- Compare with GW parametrizations
- Compare with hi-res models
- Compare with remote sensing wave data
- Examine the physics of GW



Internal data checks

- Vertical displacement
 - Vertical velocity
 - Potential temperature
- Pressure
 - Static P corrected for altitude and Coriolis force
 - Bernoulli equation using wind speed
- Energy flux (EP relationship)
 - $EF_z = \langle p'w' \rangle$
 - $EF_{z2} = -U * MF_x - V * MF_y$
- Mean W over the sea
- EF and MF direction

WRF "Long Run"

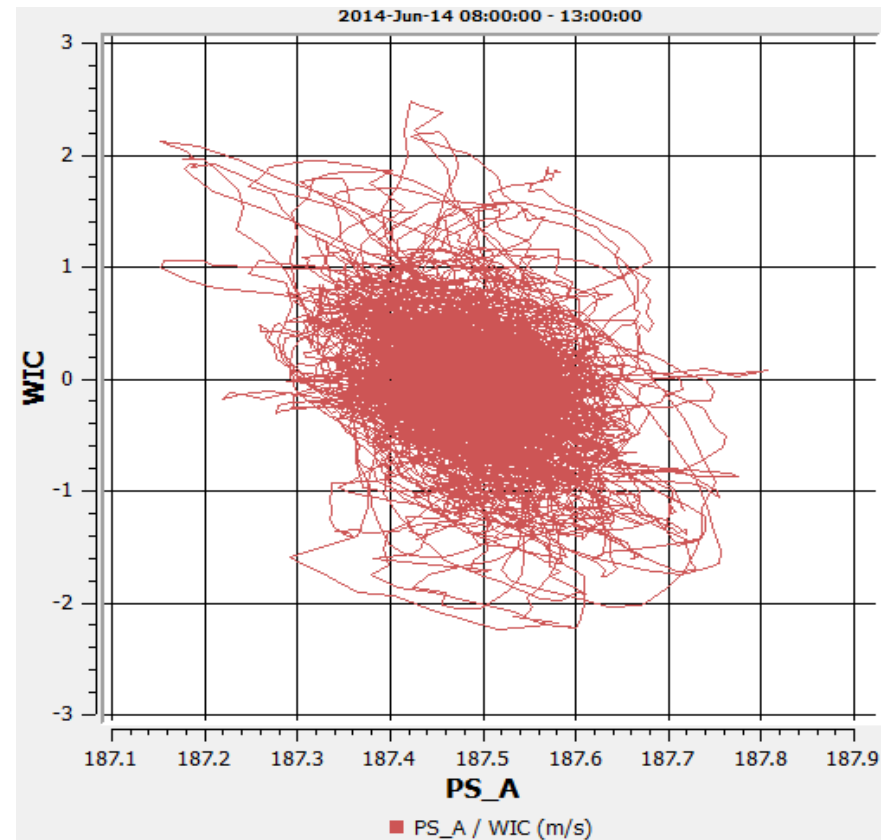
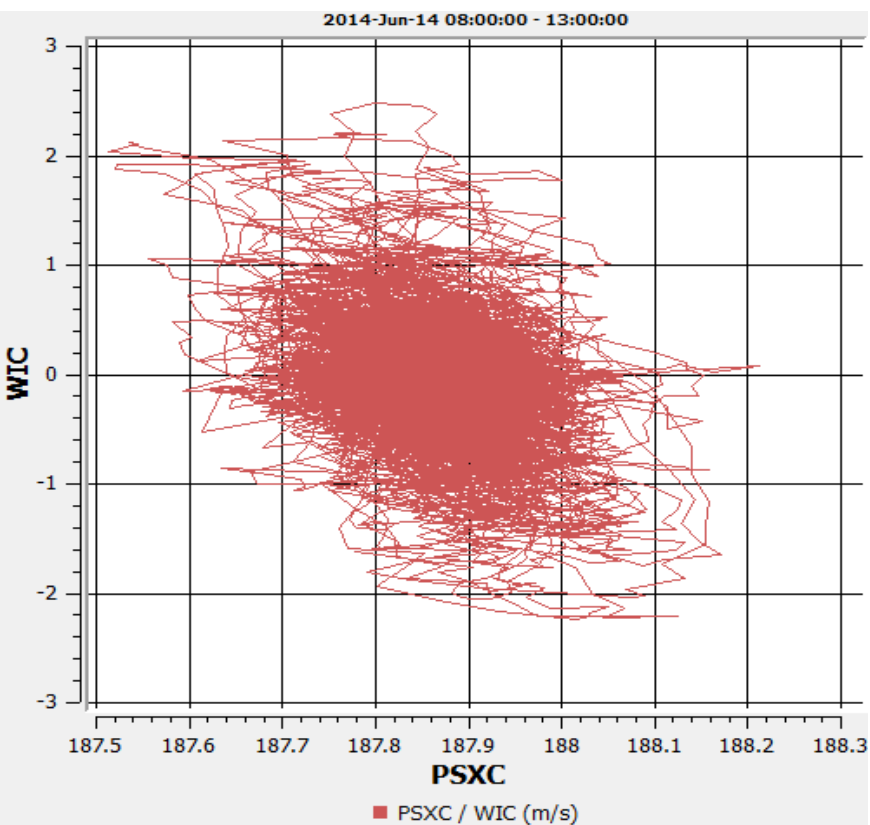


Results of setting $P_{static}'=0$

- One potentially reasonable assumption is to set the static pressure perturbation equal to zero. This is the assumption that the aircraft maintains itself on a constant pressure surface. However:
- This assumption leads to a large negative bias in the vertical energy flux $EF_z = \langle p'w' \rangle$, because of a systematic negative correlation between P_{static} and WIC. This is due to the aircraft altitude responding to vertical air motion.

RF04: Raw Pstatic vs WIC

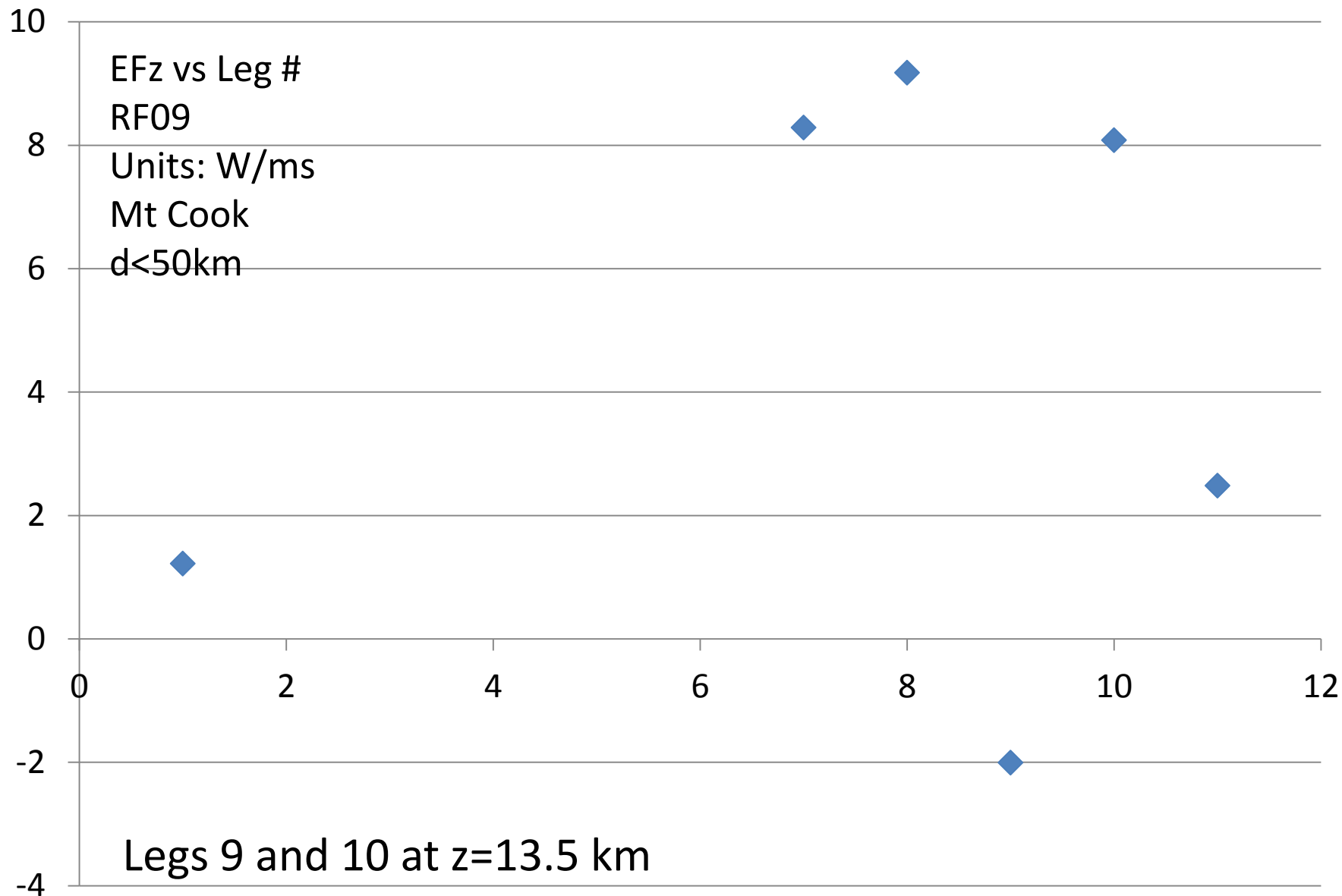
CC \sim -0.4



Aircraft leaves the constant pressure surface by +/- 0.2 hPa

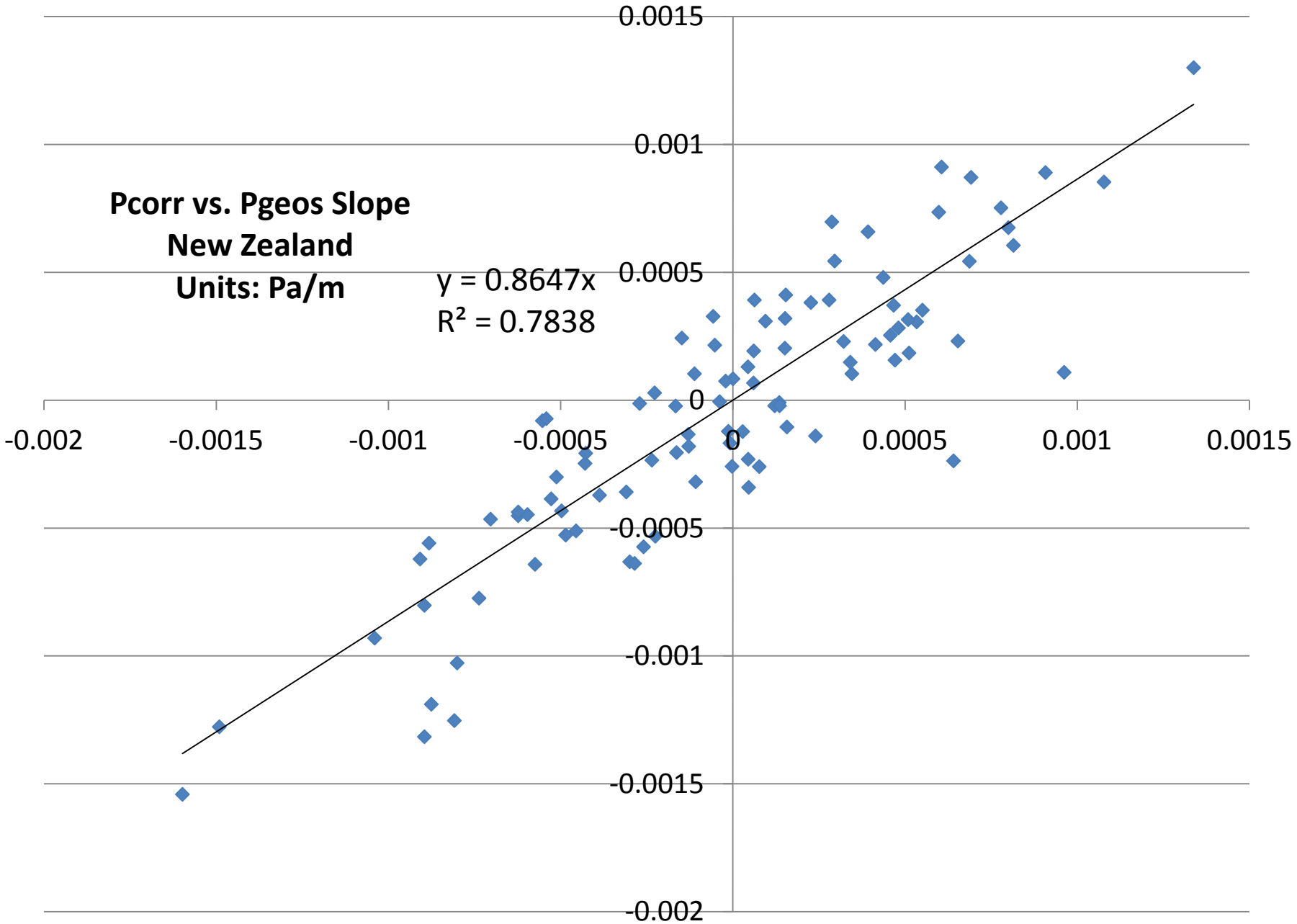
Instrument Redundancy

- Momentum and Energy Fluxes require: u, v, w, p, z
- In the Preliminary Deepwave data set, the only useful redundant measurement is static pressure (PSXC and PS_A). For u, v, w, z we have only: UIC, VIC, WIC from the nose cone and GGALT from Omnistar.
- In the final data set, with the gust pod recalibrated, we hope to have an additional u, v, w, p data set
- It seems as if the Omnistar satellite DGPS will give $z = \pm 20\text{cm}$ accuracy for altitude (z). For two flights, we will have redundancy from the ground station DGPS.

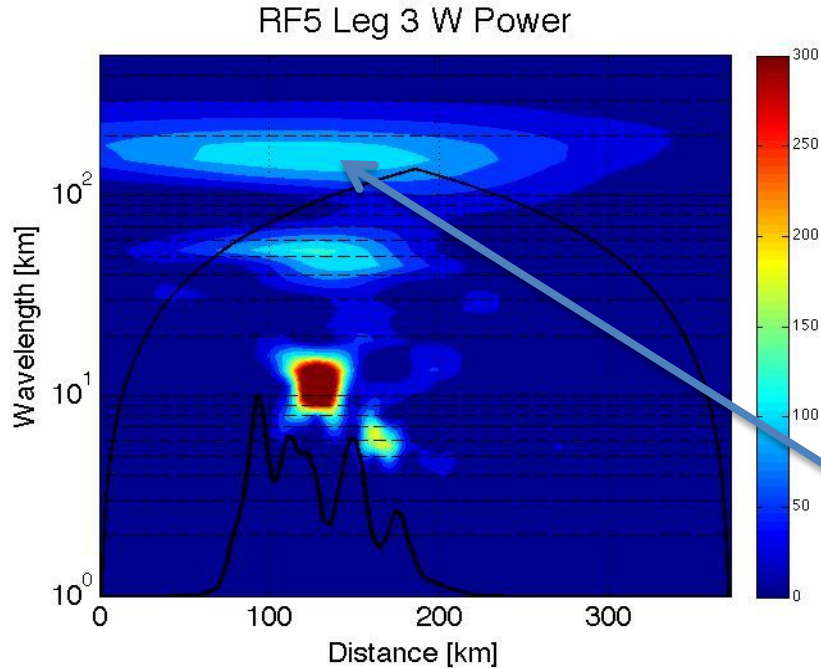


**Pcorr vs. Pgeos Slope
New Zealand
Units: Pa/m**

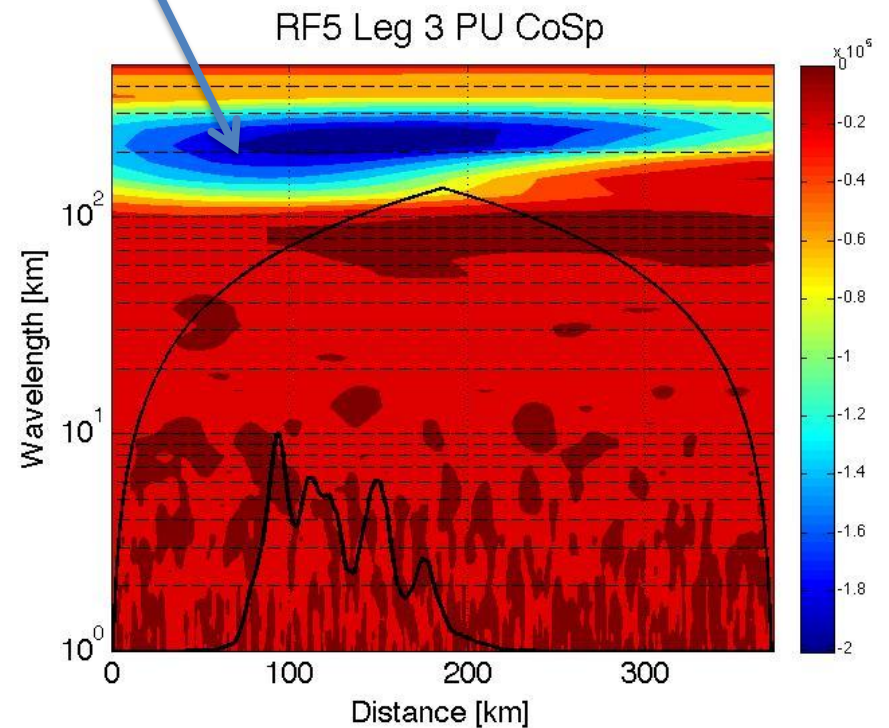
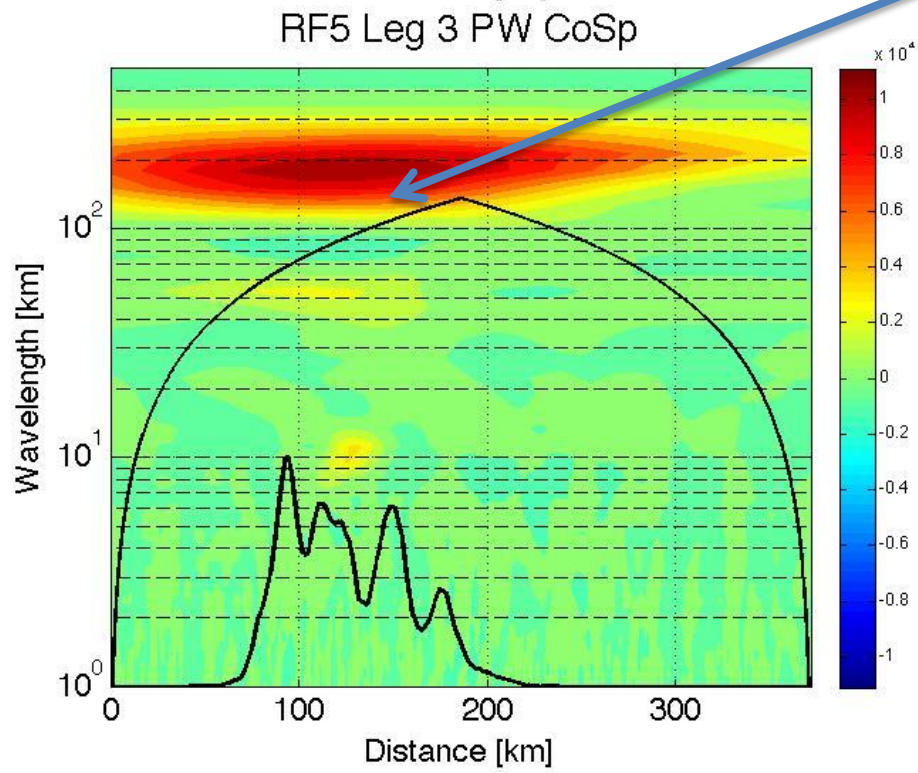
$y = 0.8647x$
 $R^2 = 0.7838$



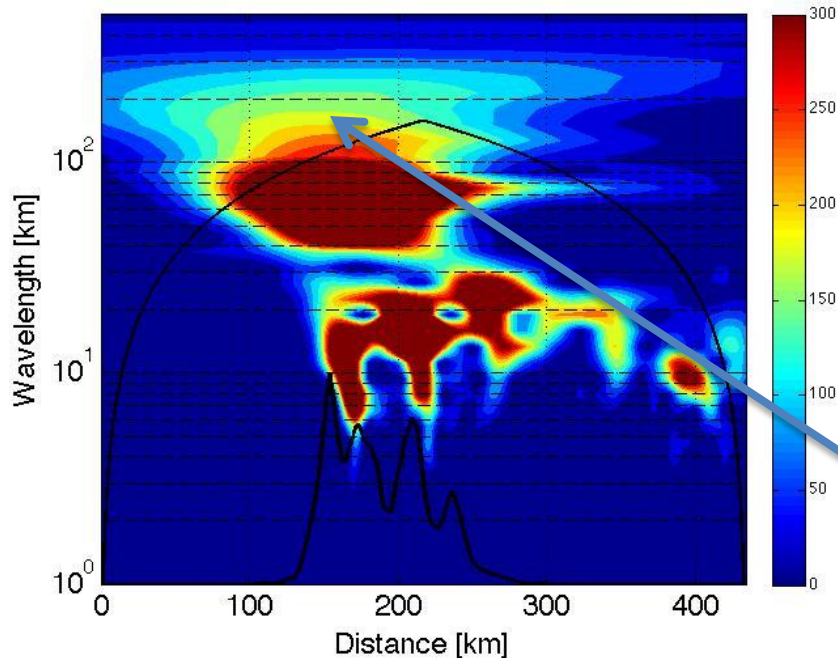
Wavelet Analysis of RF05; Leg 3 @z=12.2km



Flux-carrying Waves



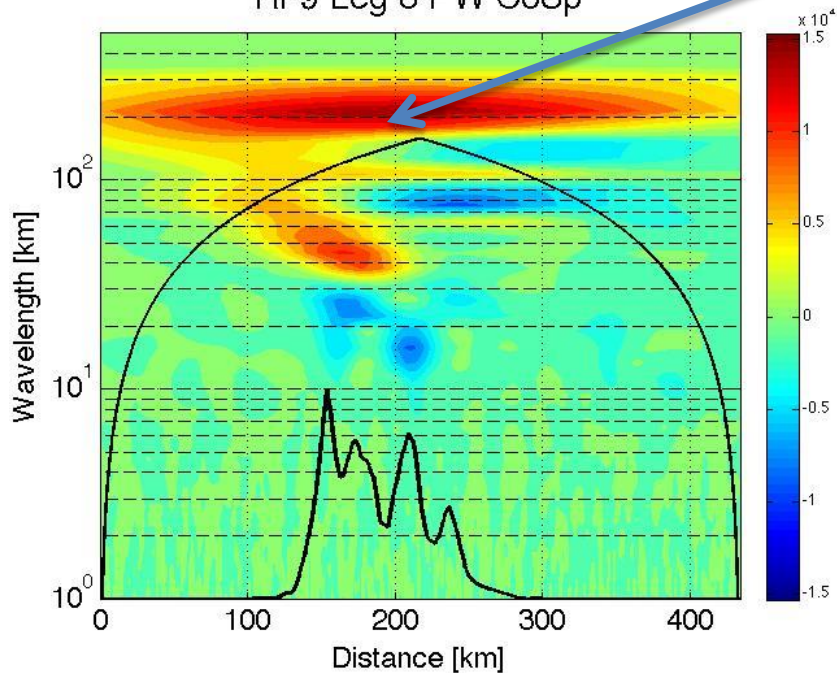
RF9 Leg 8 W Power



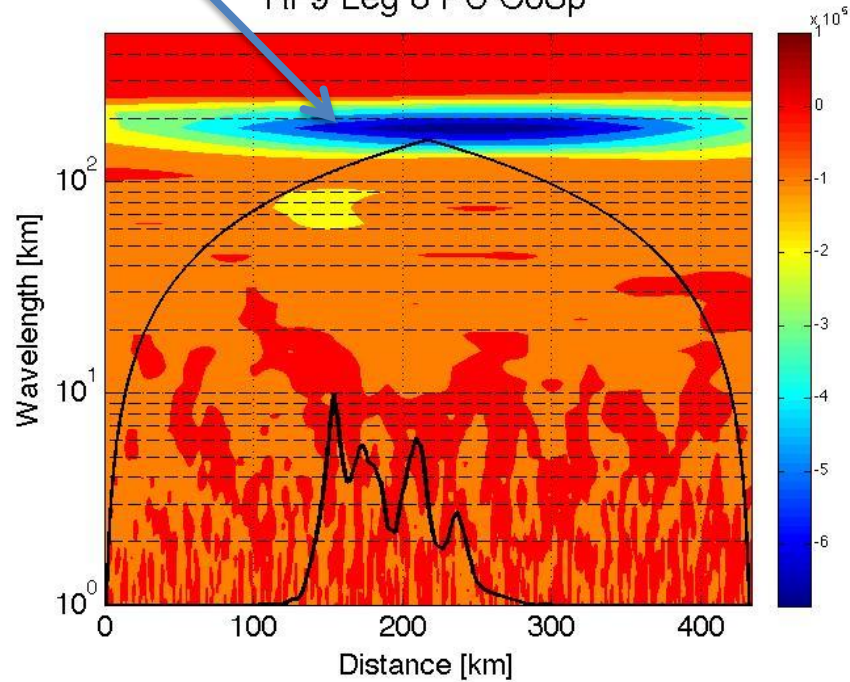
Wavelet
Analysis of
RF09; Leg 8
@z=12.2km

Flux-carrying Waves

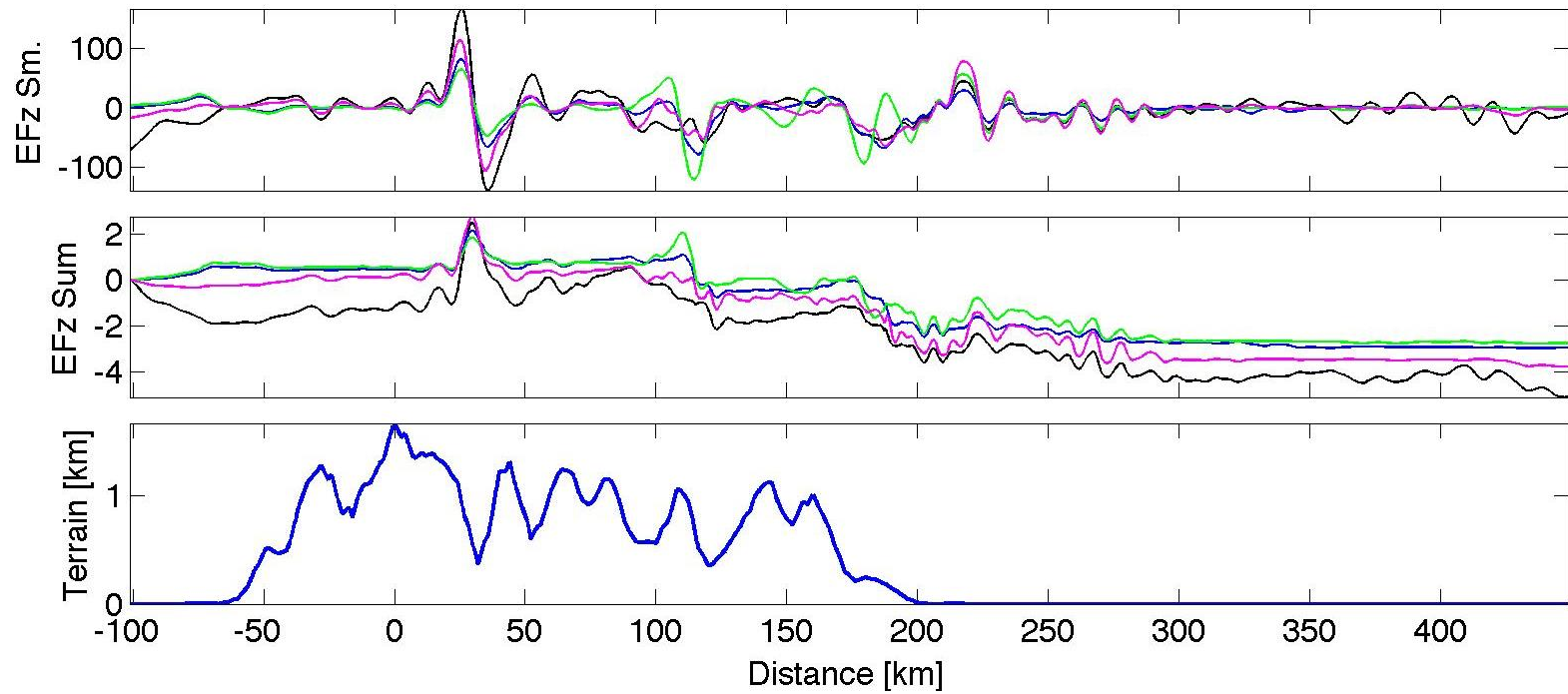
RF9 Leg 8 PW CoSp



RF9 Leg 8 PU CoSp



RF16 Leg 4: $EF_z \sim -4W/m^2$



Results of pressure redundancy test (PSX->PSA)

- Reduces EFz by 23%
- Degrades EP-check slightly
- Maintains qualitative checks
 - EFhor direction
 - Ranking flights by energy flux
- PSX is probably better than PSA