Multi-functional Airborne Raman Lidar (MARLi) and 5-Beam Airborne Doppler Radar (ADL)

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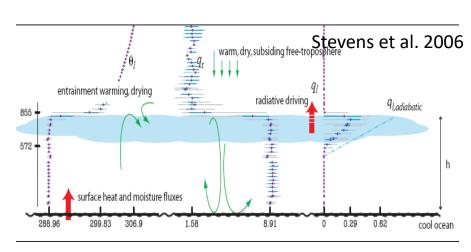
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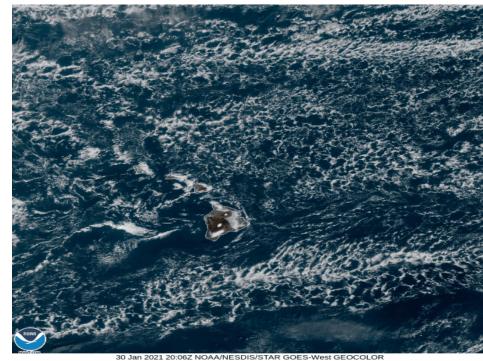
Supported By NSF

(Bradley F. Smull, Nicholas Anderson, and Shree Mishra)

The Needs of Simultaneous PBL Temperature, Water Vapor, and Wind Measurements

Cloud topped PBL





Multi-function Airborne Raman Lidar (MARLi) and Compact Raman Lidar (CRL)

CRL

- Laser: 50 mJ/150 mJ at 30 Hz
- 12-inch telescope
- First flight in 2010





MARLi

- Laser: 220 mJ at 100 Hz
- 16-inch telescope
- First flight in 2016



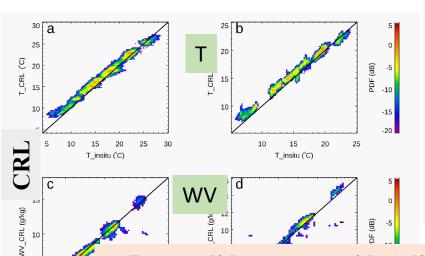
Simultaneously water vapor, temperature, and aerosol measurements.

Funded by NSF

Raman Lidar Measurement Validation

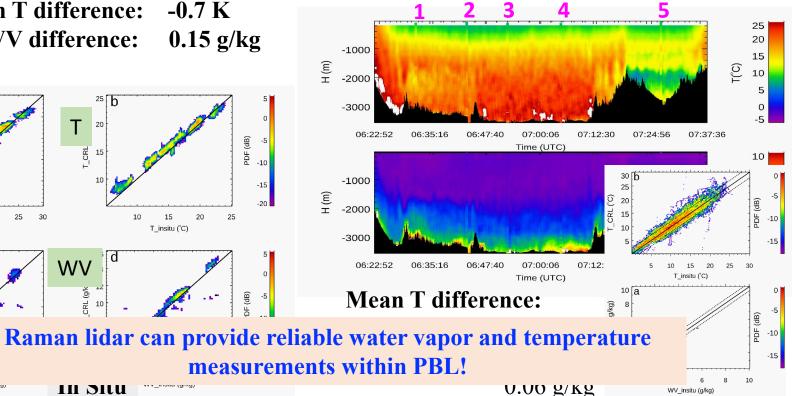
CHEESEHEAD In Situ Measurements

Mean T difference: Mean WV difference: $0.15 \, g/kg$

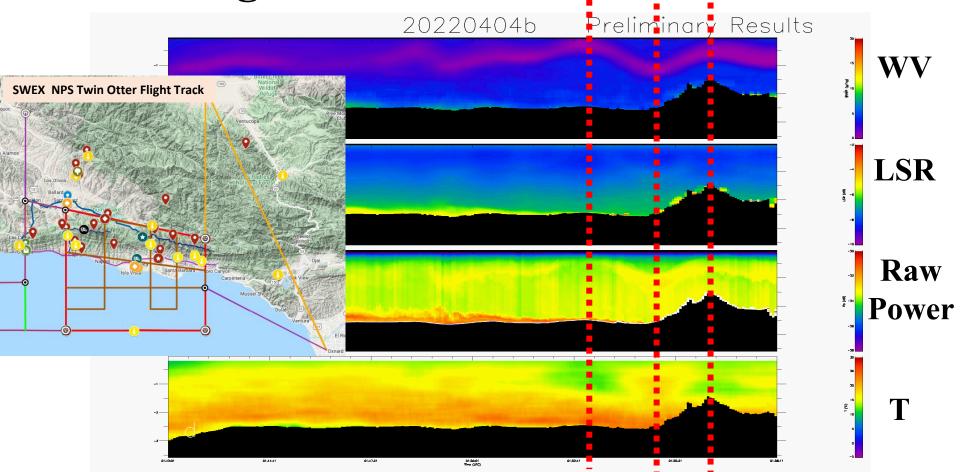


III DILU

SWEX Dropsonde Measurements



Resolving Sub-kilometer PBL Variations

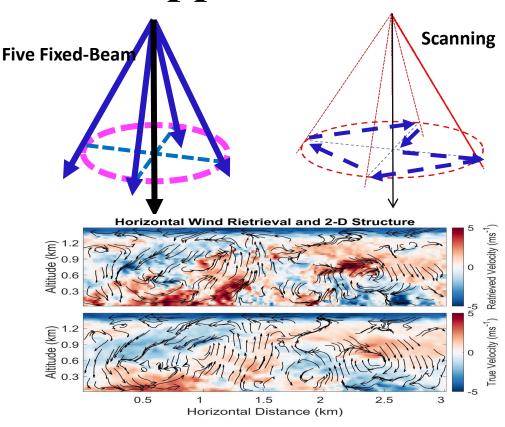


Multi-beam Airborne Doppler Lidar

- Aircraft speed range: 50—160 m/s
- Ground-relative atmospheric wind speed: ±80 m/s
- Measurement Range: 15 km maximum range (12 km measurable range)
- Along beam resolutions: selectable 18-90m, or mixed at different ranges
- Temporal resolution: 10 Hz and no deadtime between profiles

Data System

- ❖ Band-width: 30-300 MHz
- ❖ Sampling rate: 1G/s
- ❖ FFTs: 4096 points
- ❖ 200 range gates per profile
- Keep full power spectrum for post-data



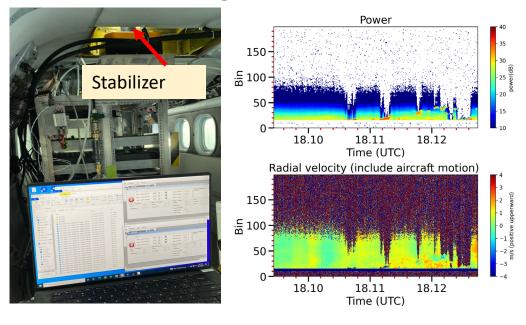
Retrieved using foreword, nadir, and backwards beams at 30deg elevations, flying crosswind in 15 m/s mean wind

ADL Testing

Ground-based Five-beam Testing

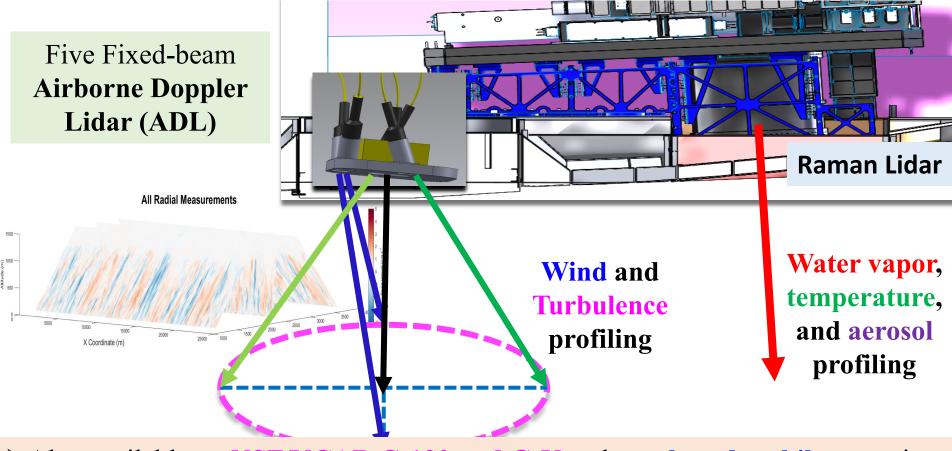


Two-Beam testing on the NPS Twin Otter



Will be Deployed on NSF/NCAR C-130 for the CAESAR and NASA P-3 for the ARCSIX in 2024.

Future Wyoming King Air PBL Observations



➤ Also available on NSF/NCAR C-130 and G-V and van-based mobile operations.