The Deep Propagating Gravity Wave Experiment (DEEPWAVE)

Science Overview and Approach

U.S. Pls: Dave Fritts, Ron Smith, Mike Taylor, Jim Doyle, Steve Eckermann, and Steve Smith

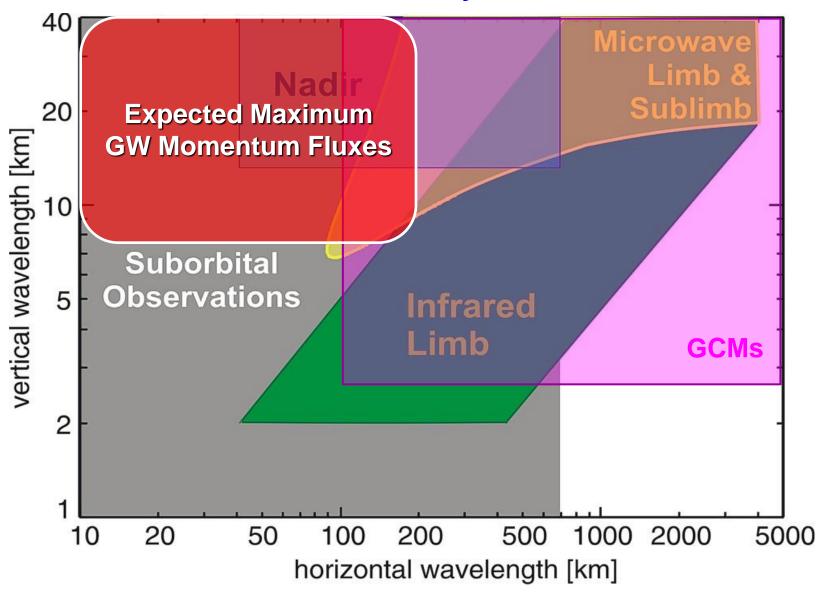
and international colleagues from

Germany, New Zealand, Australia, and UK

DEEPWAVE Motivation: Why are deep propagating GWs important?

- GWs account for primary vertical energy & momentum transport at all levels
- GCM parameterizations of GWs are known to be seriously deficient
- The important GWs are not resolved by satellite measurements or GCMs
- Better GW parameterizations require improved understanding, coordinated measurements and modeling studies

GW scale sensitivity and needs

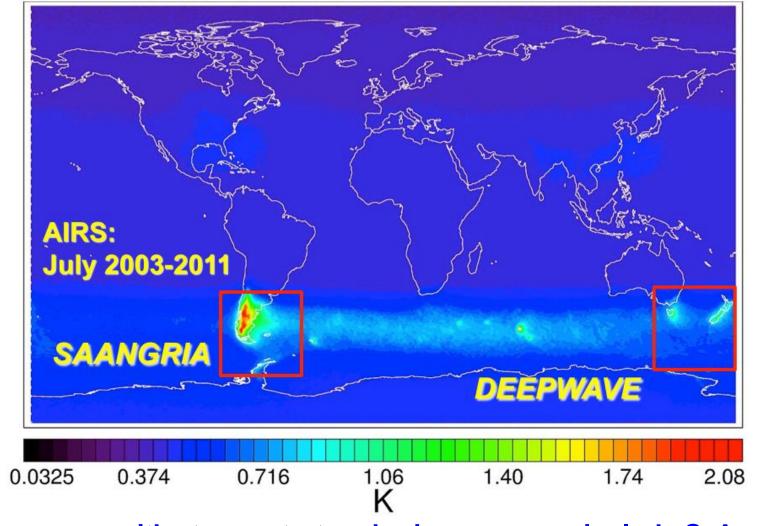


- New measurements are needed to identify and quantify deep GW dynamics
- Efforts are needed to calibrate satellite measurement capabilities

DEEPWAVE Approach:

- Perform comprehensive measurements at a location where these dynamics have large responses and can be quantified with confidence
 - desire sensitivity to several major GW sources
- Expand measurement capabilities to dramatically increase data accuracy and vertical extent – spanning altitudes of ~0-100 km
- Bring additional U.S. and international resources to enhance the value to the research community
- Include extensive forecasting and modeling activities for better understanding

Site selection focused on Austral Winter GW "Hot Spots" (stronger responses, minimal SSW risk compared to N.H.)



GW sources with strong stratospheric responses include S. Andes, Antarctic Peninsula, New Zealand, and Tasmania

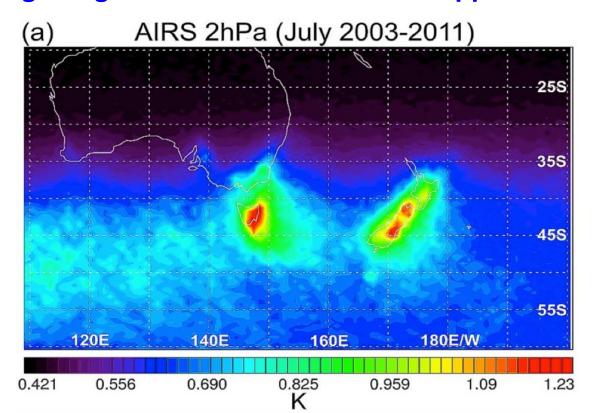
- S. Andes/AP (SAANGRIA) judged not feasible for NGV operations

DEEPWAVE "Region of Airborne Operations" (RAO) is the 2nd largest SH GW hotspot on Earth

major GW sources include:

- topography (NZ, Tasmania, islands)
- circumpolar jet (Southern Ocean)
- frontal systems

New Zealand is a very good operational environment with good ground-based instrument support

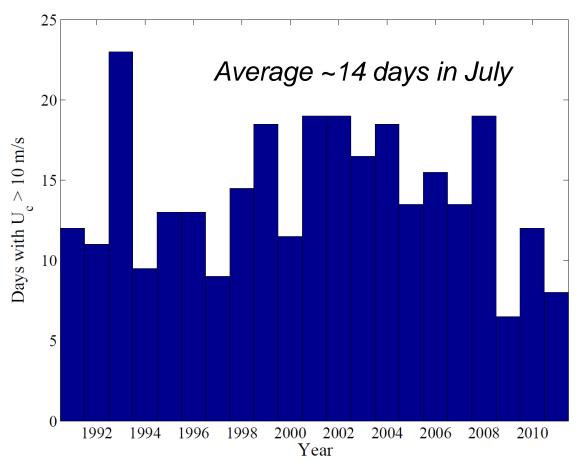


Deep GW Propagation over New Zealand

high frequency of multi-day strong forcing events
 expect ~10 (minimum 3, maximum ~15) events
 with U > 15 ms⁻¹ in 6-week campaign

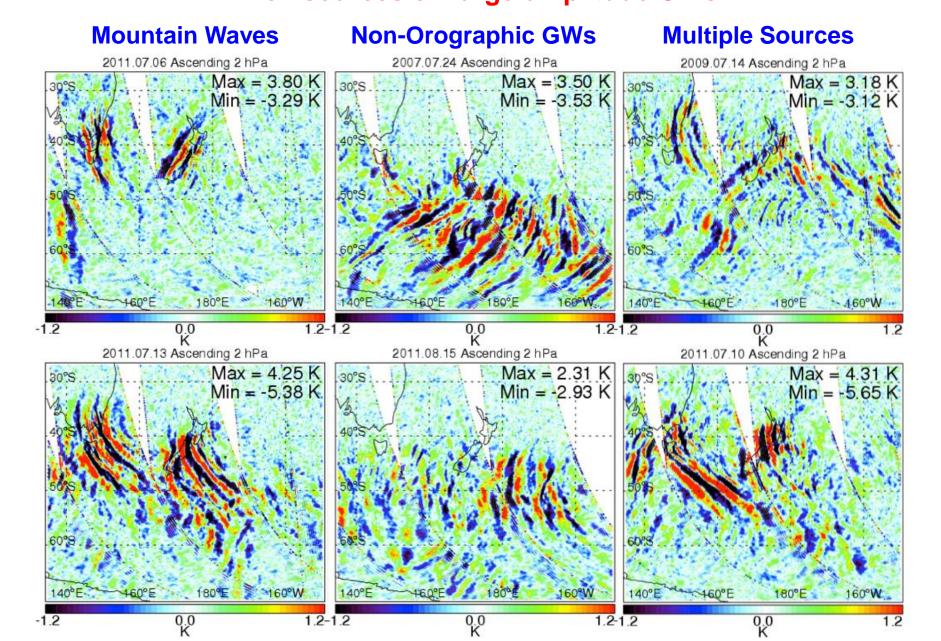
Frequency of 700 hPa winds >10 m s⁻¹ at Invercargill, New Zealand

ERA Reanalysis (July 1991-2011)



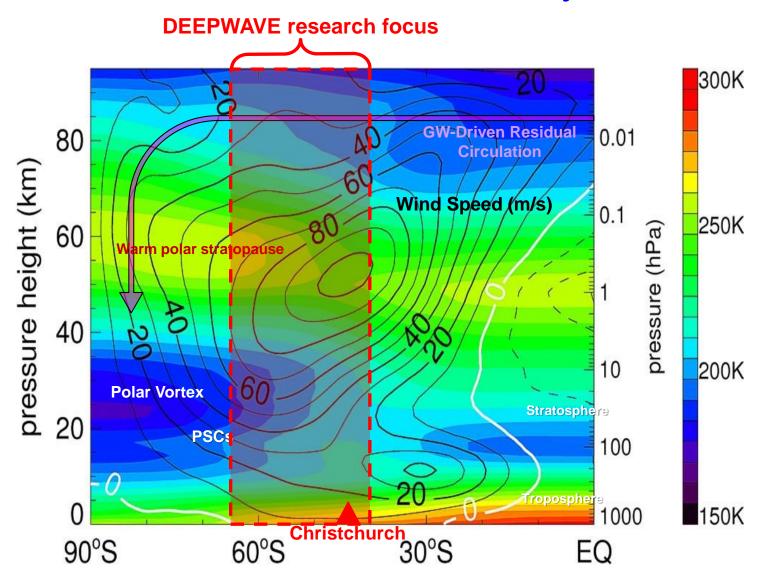
- Mountain wave propagation to high altitudes is common in S. Hemisphere
- Strong flows over New Zealand and Tasmania are prominent GW sources

GWs at ~41 km over New Zealand & the Southern Ocean - rich sources of large-amplitude GWs

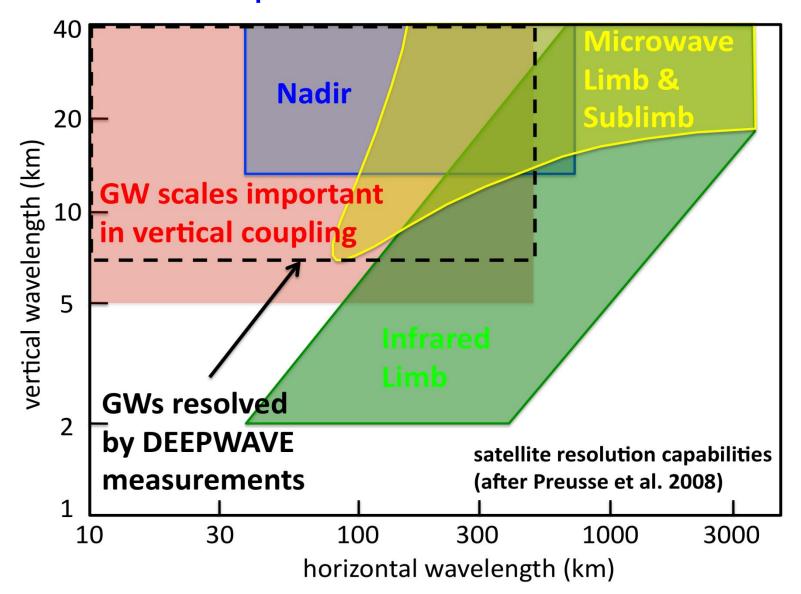


Austral Winter also provides a <u>stronger zonal jet and strong</u> <u>GW propagation channel</u> enabling GWs to penetrate to very high altitudes

- in an ideal natural laboratory



New DEEPWAVE instruments will provide sensitivity to the dominant GW scales relevant to quantifying GW influences and parameterization needs



DEEPWAVE Field Campaign and Measurement Plans - field program 5 June – 21 July 2014

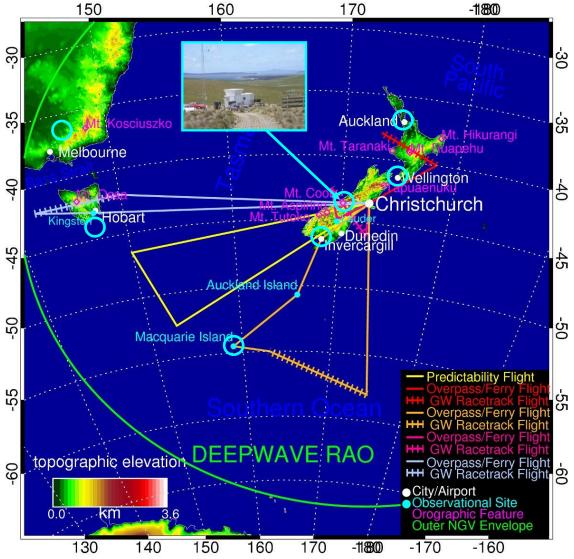
NSF/NCAR Gulfstream V (NGV) with new lidars and MTM measuring from ~15 – 100 km



DLR Falcon with Doppler lidar measuring from ~0 - 11 km







DEEPWAVE Instrumentation - all demonstrated in Feb. 2013 NGV test flights

Instrument	Parameters	Altitudes	Impact
In situ instruments (gust probe, GPS)	Winds, temperature, O_3 , aerosol, humidity • 1-5 Hz ($\Delta x \sim 50-250 \text{ m}$)	Flight level (5-13 km)	Along-track hi-res GW & turbulence data
Dropsondes	Wind & temperature profiles • Δz~100 m	Below aircraft (0-13 km)	Flow environment, GW structure below flight level
Microwave Temperature Profiler (MTP)	Temperature profiles •±1-2 K, Δz ~0.7-3 km, 10-15 s integration (Δx ~2-4 km)	~5-20 km	GW structure above & below GV
Rayleigh lidar	Temperature profiles •±2-8 K, Δz~2 km, 20-s integration (Δx~4 km)	<i>T</i> ~30-50+ km	GW structure GW-induced PSCs
Sodium (Na) resonance lidar	Na densities, temperature • \pm 1-3 K, Δ z~3-5 km, 20-s int. (Δ x~4 km) vertical wind • \pm 1-3 m/s, Δ z~3-5 km, 20-s int. (Δ x~5 km)	~15-30 km ~84-96 km	GW structure
Mesospheric Temperature Mapper (MTM)	All sky OH airglow and temperature •±2 K, 2-s integration/TDI (Δx~1 km)	~87 km	2D map of GW and instability structures, propagation directions

Existing Facility Instruments

New Facility instruments recently developed for DEEPWAVE

DEEPWAVE PIs have developed 3 new NGV instruments to extend DEEPWAVE measurements from ~0 to 100 km

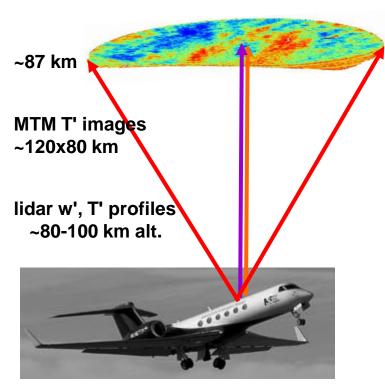
- Rayleigh lidar T and T'(z,t) ~30 60 km
- Na resonance lidar w' and T'(z,t) ~15-30 km and ~80-100 km)
- Mesosphere Temperature Mapper (MTM) T and T'(x,y,t) ~87 km

Rayleigh and Na lidars (Biff Williams, GATS)



MTM (Mike Taylor, USU)



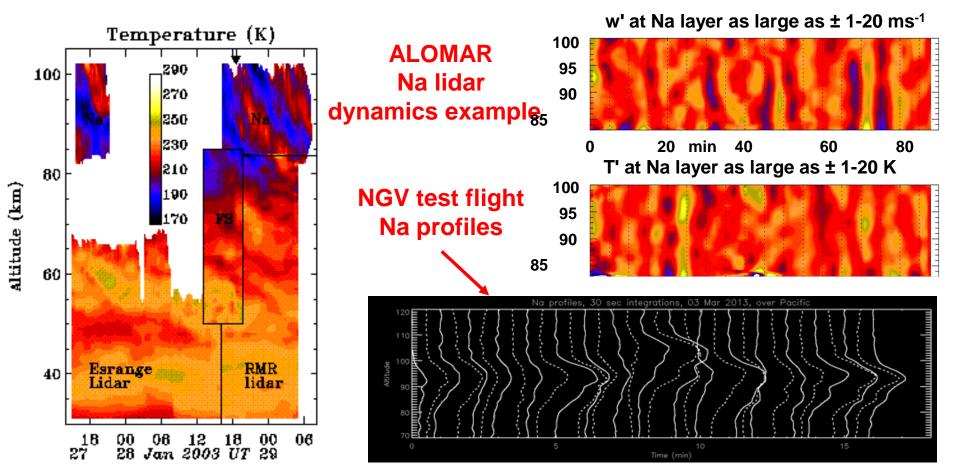


NGV UV and sodium lidar measurements

UV lidar: ~5 W pulsed densities (temperatures) ~30-60 km

Na lidar: ~14 W CW, pulsed/32-channel scanned vert. winds, temps. – double-edge filter, Na res. ~15 – 30 km, ~80 – 100 km





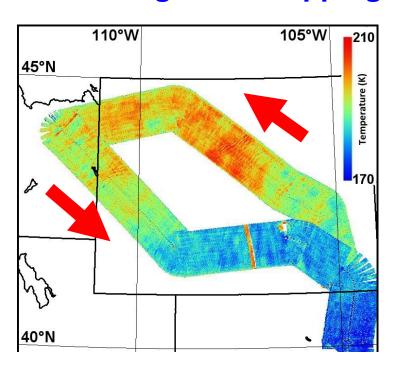
NGV MTM measurements ~87 km OH airglow

- continuous horizontal map of temperature: ∆x, ∆y ~0.5 km (~120 km along track, ~80 km cross track)
- temporal span ~10 min to track evolution of small-scale features

MTM temperatures

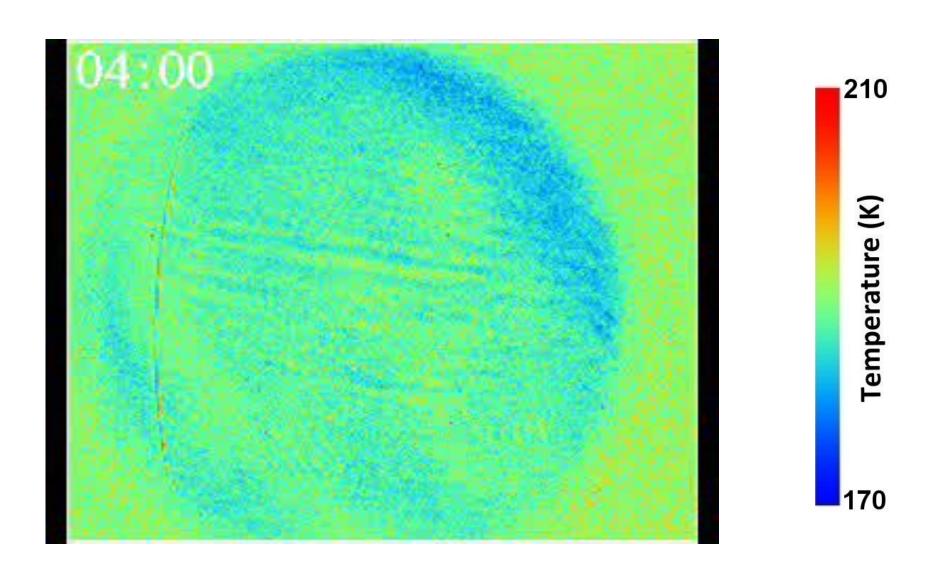
205 (X) Lemberature (K)

MTM along-track mapping



~6-hr test flight

Example MTM OH Temperature Movie



DEEPWAVE measurements will also be augmented through DLR participation with an airborne Doppler lidar, in-situ measurements, dropsondes, balloon soundings, and a ground-based Na lidar

DLR Doppler lidar and dropsondes will yield:

- mean winds, GW structure, amplitudes, and momentum fluxes ~0 to 11 km

DLR ground-based Na lidar will yield:

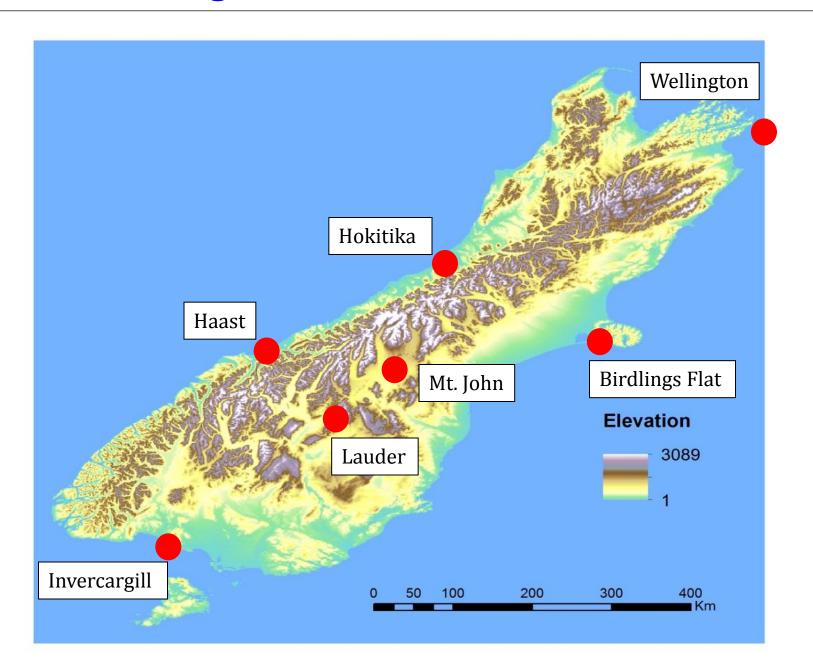
- Rayleigh temperatures ~5-70 km

- radial winds ~80-105 km, if Na resonance capabilities are in place





DEEPWAVE ground-based measurement sites



DEEPWAVE ground-based measurements

Birdling's Flat

- meteor radar (J. Baggaley) - horizontal winds ~80-100 km (auto.)

Haast

- portable sounding system, DLR/NCAR??? (manned)

Hokitika

- NCAR ISS - balloons to ~30 km; 449 MHz BLR, winds to ~5+ km (manned)

Lauder

- AMTM (M. Taylor) GW OH structure, T(x,y,t) at ~87 km (auto.)
- Na lidar, (B. Kaifler) T(z,t) to ~30-100 km, $U_h(z,t)$ ~80-100 km, one comp. (manned)
 - DLR balloons (A. Dornbrack) (manned)
 - Airglow imager (S. Smith) GW airglow structures, ~87-95 km, ~300 km (auto.)

Mt. John

- airglow imager (S. Smith) GW airglow structures, ~87-95 km, ~300 km (auto.)
- FPI (G. Hernandez) ??? (auto.)

Other balloon soundings to ~30 km at various sites

- NZ Invercargill, Wellington??, Aukland?? (other per.)
- Australia Kingston, Aukland Is., Macquarie Is. (other per.)

AAD (Australia)

- Hobart, TAS Rayleigh lidar, sondes (other per.)
- Davis, Ant. (68.6°S, Australia) Antarctic radars, lidar, airglow (other per.)

DEEPWAVE and correlative measurement capabilities 100 $w'(x,z) \& T'(x,z) \sim 80-100 \text{ km}$ NGV sodium lidar **NGV MTM** T'(x,y)~87 km 80 **MF** radar meteor radar airglow imager meteor radar Ray./Na lidars airglow imager (Davis, ANT) (NZ, Tasmania) **50** NGV Rayleigh lidar $\rho'(x,z)$, T'(x,z) ~30-60+ km **MST** radar Ζ radiosondes radiosondes radiosondes (km) NGV sodium lidar w'(x,z) & T'(x,z) ~15-30 km ISS 20 NGV in-situ winds, MTP T'(x,z) dropsondes 10 Falcon in-situ winds, lidar winds, GW momentum fluxes. S. Alps **Antarctica** dropsondes Davis (68.6°S) 60°S Macquarie Is.(54.6°S) 50°S CC/NZ (43.5°S) 40°S

Forecasting and modeling support for DEEPWAVE

NOGAPS-ALPHA global (S. Eckermann, NRL)
- data assimilation, forecasting

COAMPS deep nested mesoscale (J. Doyle, NRL)- data assimilation, forecasting, predictability

ECMWF forecasts (A. Dörnbrack, DLR) - support for flight planning

NIWA forecasts (M. Uddstrom, NIWA)
- support for flight planning and data analyses

WRF (R. Smith, Yale, and A. Dörnbrack, DLR) - orographic gravity wave forcing, lower altitudes

Finite-Volume regional (GATS, D. Fritts)
- compressible/anelastic, deep (~0-300 km) GW wave responses, interactions & instabilities

Spectral fine scale (GATS, D. Fritts)
- GW interactions, instabilities, and turbulence

DEEPWAVE Flight Forecasting

- successful "Dry Run" exercise 5-15 Aug. 2013
- major contributors NOGAPS, COAMPS, ECMWF

